

論理関数の Bi-decomposition について

笹尾勤

九州工業大学情報工学部

Jon. T. Butler

Naval Postgraduate School

論理関数 f が $h(g_1(X_1), g_2(X_2))$ の形で表現できるとき、 f は disjunctive bi-decomposition をもつという、ここで、 X_1 と X_2 は共通部分を持たない変数の集合を表し、 h は任意の二変数論理関数である。また、 f が $f(X_1, X_2, x) = h(g_1(X_1, x), g_2(X_2, x))$ と表現できるとき、 f は non-disjoint bi-decomposition をもつという、ここで、 x は共通変数を表す。本論文では、論理関数が bi-decomposition をもつか否かを、分解表を用いずに高速に検出する方法を述べる。また、分解可能な関数の個数について述べる。

On Bi-Decompositions of Logic Functions

Tsutomu SASAO

and

Jon T. Butler

Kyushu Institute of Technology

Naval Postgraduate School

Iizuka 820, Japan

Monterey, CA 93943, U.S.A.

A logic function f has a disjoint bi-decomposition iff f can be represented as $f = h(g_1(X_1), g_2(X_2))$, where X_1 and X_2 are disjoint set of variables, and h is an arbitrary two-variable logic function. f has a non-disjoint bi-decomposition iff f can be represented as $f(X_1, X_2, x) = h(g_1(X_1, x), g_2(X_2, x))$, where x is the common variable. In this paper, we show a fast method to find bi-decompositions without using decomposition charts. Also, we enumerate the number of functions having bi-decompositions.

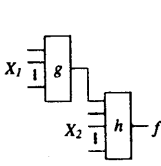


Figure 1.1: A simple disjoint decomposition.

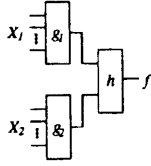


Figure 1.2: A disjoint bi-decomposition.

		$X_1 = (x_1, x_2)$			
		00	01	10	11
$X_2 = (x_3, x_4)$	00	0	0	0	1
	01	0	0	0	1
	10	0	0	0	1
	11	1	1	1	0

(a)

		$X_1 = (x_1, x_2)$			
		00	01	10	11
$X_2 = (x_3, x_4)$	00	0	0	0	0
	01	0	1	0	1
	10	0	0	1	1
	11	0	1	1	0

(b)

Figure 2.1: Decomposition chart.

I Introduction

Functional decomposition is a basic technique to realize economical networks [1]. If the function f is represented as $f(X_1, X_2) = h(g(X_1), X_2)$, then f can be realized by the network shown in Fig. 1.1. To find such a decomposition, a decomposition chart with 2^{n_1} columns and 2^{n_2} rows are used, where n_i is the number of variables in X_i ($i = 1, 2$). When n is large, the decomposition chart is too large to build. Recently, a method using BDDs has been developed [12, 18]. This greatly reduces memory requirements and computation time. However, it is still time consuming, since we have to check all the $\binom{n_1+n_2}{n_1}$ partitions of $n = n_1 + n_2$. In this paper, we consider bi-decompositions of logic functions, a restricted class of functional decompositions, that have the form $f(X_1, X_2) = h(g_1(X_1), g_2(X_2))$. Fig. 1.2 shows the realization of this decomposition.

The reasons we consider bi-decompositions are as follows:

- 1) Some programmable logic devices have two-input logic elements in the outputs [6, 13].
- 2) If f has a bi-decomposition, then the optimization of the expression is relatively easy.
- 3) If f has no bi-decomposition, then the computation time is quite small.

A restricted class of bi-decompositions has been considered by [7]. The goals of this paper are

- 1) Present a fast method for finding bi-decompositions.
- 2) Enumerate the functions that have bi-decompositions.

Most of the proofs are omitted. They can be available from authors.

II Disjoint Bi-Decomposition

Definition 2.1 Let $X = (X_1, X_2)$ be a partition of the variables. A logic function f has a disjoint bi-decomposition iff f can be represented as $f(X_1, X_2) = h(g_1(X_1), g_2(X_2))$, where h is any two-variable logic function.

If f has a disjoint bi-decomposition, then f can be realized by the network shown in Fig. 1.2.

Definition 2.2 Let $X = (X_1, X_2)$ be a partition of the variables. Let n_1 and n_2 be the number of variables in X_1 and X_2 , respectively. A decomposition chart of the function f for a partition (X_1, X_2) consists of 2^{n_1} columns and 2^{n_2} rows of 0s and 1s. The 2^{n_1} distinct binary numbers for X_1 are listed across the top, and the 2^{n_2} distinct binary numbers for X_2 are listed down the side. The entry for the chart corresponds to the value of $f(X_1, X_2)$.

Example 2.1 Two decomposition charts for the function $f(x_1, x_2, x_3, x_4) = x_1x_2 \oplus x_3x_4$ are shown in Fig. 2.1 (a) and (b). (End of Example)

Note that the decomposition chart is similar to the Karnaugh map with a different ordering for the cell locations.

Definition 2.3 The number of distinct column (row) patterns in the decomposition chart is called column (row) multiplicity.

Example 2.2 In Fig. 2.1 (a), the row and column multiplicities are two. In Fig. 2.1 (b), the row and column multiplicities are four. (End of Example)

Definition 2.4 Let $\mu(f : X_1, X_2)$ be the column multiplicities for f with respect to X_1 and X_2 . Let $\mu(f : X_2, X_1)$ be the row multiplicities for f with respect to X_1 and X_2 .

Theorem 2.1 [1, 3] f has a disjoint bi-decomposition of form $f(X_1, X_2) = h(g_1(X_1), g_2(X_2))$ iff $\mu(f : X_1, X_2) \leq 2$ and $\mu(f : X_2, X_1) \leq 2$.

III Non-Disjoint Bi-Decomposition

Definition 3.1 Let X_1 and X_2 be disjoint sets of variables, and let x be disjoint from X_1 and X_2 . A logic function f has a non-disjoint bi-decomposition iff f can be represented as $f(X_1, X_2, x) = h(g_1(X_1, x), g_2(X_2, x))$, where h is a two-variable logic function. In this case, x is called the common variable.

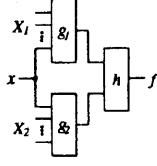


Figure 3.1: A non-disjoint bi-decomposition.

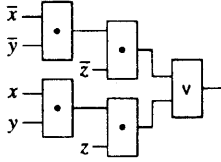


Figure 3.2: A realization of $f(x, y, z) = \bar{x}\bar{y}\bar{z} \vee xyz$.

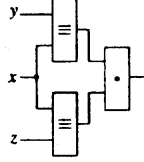


Figure 3.3: Non-disjoint bi-decomposition for $f(x, y, z) = \bar{x}\bar{y}\bar{z} \vee xyz$.

A function f with a non-disjoint bi-decomposition can be realized by the network shown in Fig. 3.1

Lemma 3.1 Let $X = (X_1, X_2, x)$ be a partition of the input variables. Let $h(g_1, g_2)$ be an arbitrary logic function of two variables. Then,

$$h(g_1(X_1, x), g_2(X_2, x)) = \bar{x}h(g_1(X_1, 0), g_2(X_2, 0)) \vee xh(g_1(X_1, 1), g_2(X_2, 1)).$$

(Proof) For $x = 0$, the left-hand side of the equation is $h(g_1(X_1, 0), g_2(X_2, 0))$, and the right-hand side of the equation is also $h(g_1(X_1, 0), g_2(X_2, 0))$. Similarly, for $x = 1$, and the equality holds. ■

Definition 3.2 Let x be the common variable of the non-disjoint bi-decomposition. Let $f(X_1, X_2, a)$ be a sub-function, where x is set to a 0 or 1.

Theorem 3.1 $f(X_1, X_2, x)$ has a non-disjoint bi-decomposition of the form $h(g_1(X_1, x), g_2(X_2, x))$ iff $f(X_1, X_2, 0)$ and $f(X_1, X_2, 1)$ have disjoint bi-decompositions $h(g_{01}(X_1), g_{02}(X_2))$ and $h(g_{11}(X_1), g_{12}(X_2))$, respectively.

Example 3.1 Consider the three-variable function: $f(x, y, z) = \bar{x}\bar{y}\bar{z} \vee xyz$. Suppose modules that realizes any function of two variables can be used. The straightforward realization shown in Fig. 3.2 requires five modules. The Shannon expansion with respect to x is $f(x, y, z) = \bar{x}f(0, y, z) \vee xf(1, y, z)$, where $f(0, y, z) = \bar{y}\bar{z}$, and $f(1, y, z) = yz$. Note that both $f(0, y, z)$ and $f(1, y, z)$ have bi-decompositions with $h(x, y) = xy$. Since, $g_1(x, y) =$

		$X_1 = (x_1, x_2)$			
		00	01	10	11
$X_2 = (x_3, x_4)$	00	1	0	0	0
	01	1	0	0	0
	10	1	0	0	0
	11	0	1	1	1

(a) $f_0 = \bar{x}_1\bar{x}_2 \oplus x_3x_4$

		$X_1 = (x_1, x_2)$			
		00	01	10	11
$X_2 = (x_3, x_4)$	00	0	0	0	1
	01	1	1	1	0
	10	1	1	1	0
	11	1	1	1	0

(b) $f_1 = x_1x_2 \oplus (x_3 \vee x_4)$

Figure 3.4: Functions in Example 3.2

$\bar{x}g_{01}(X_1) \vee xg_{11}(X_1) = \bar{x}\bar{y} \vee xy$, and $g_2(x, y) = \bar{x}g_{02}(X_2) \vee xg_{12}(X_2) = \bar{x}\bar{z} \vee xz$. We have $f(x, y, z) = g_1(x, y)g_2(x, z) = (\bar{x}\bar{y} \vee xy)(\bar{x}\bar{z} \vee xz)$. From this expression, we have the network in Fig. 3.3. This network requires only three modules. (End of Example)

Example 3.2 Consider the five-variable function $f = \bar{x}_5f_0 \vee x_5f_1$, where f_0 and f_1 are shown in Fig. 3.4. Since both f_0 and f_1 have disjoint bi-decompositions of the form $h(g_1(X_1), g_2(X_2))$, $f = \bar{x}_5f_0 \vee x_5f_1$ has a non-disjoint bi-decomposition as follows:

$$\begin{aligned} f &= \bar{x}_5\{\bar{x}_1\bar{x}_2 \oplus x_3x_4\} \vee x_5\{x_1x_2 \oplus (x_3 \vee x_4)\} \\ &= \{\bar{x}_5(\bar{x}_1\bar{x}_2) \vee x_5(x_1x_2)\} \\ &\quad \oplus \{\bar{x}_5(x_3x_4) \vee x_5(x_3 \vee x_4)\}. \end{aligned}$$

The converse is true also. (End of Example)

Up to now, we only considered the case where there is a single common variable. However, the theorem can be extended to k common variables, where $k \geq 2$.

Definition 3.3 Let X_1, X_2 , and X_3 be disjoint sets of variables. Let $f(X_1, X_2, a)$ be the sub-functions, where X_3 is set to $a \in \{0, 1\}^k$, and k denotes the number of variables in X_3 .

Theorem 3.2 Let X_1, X_2 , and X_3 be disjoint sets of variables. Then, f has a non-disjoint bi-decomposition of form

$$f(X_1, X_2, X_3) = h(g_1(X_1, X_3), g_2(X_2, X_3))$$

iff $f(X_1, X_2, a)$ has a decomposition of the form $h(g_1a(X_1), g_2a(X_2))$ for all possible $a \in \{0, 1\}^k$, where k denotes the number of variables in X_3 .

IV A Fast Method for Bi-Decompositions

In this section, we show necessary and sufficient conditions for a function to have a disjoint bi-decomposition. Then, we show efficient algorithms to find disjoint bi-decompositions. In the previous sections, $h(g_1, g_2)$ is an arbitrary two-variable logic function. To find a disjoint bi-decomposition, we need to consider only three types:

- 1) OR type: $f = g_1(X_1) \vee g_2(X_2)$,
- 2) AND type: $f = g_1(X_1)g_2(X_2)$, and
- 3) EXOR type: $f = g_1(X_1) \oplus g_2(X_2)$.

Since f has an AND type disjoint bi-decomposition iff \bar{f} has OR type disjoint bi-decomposition, we only consider the OR type and EXOR type bi-decompositions.

Definition 4.1 x and \bar{x} are literals of a variable x . A logical product which contains at most one literal for each variable is called a product term or a product. Product terms combined with OR operators form a sum-of-products expression (SOP).

Definition 4.2 A prime implicant (PI) p of a function f is a product term which implies f , such that the deletion of any literal from p results in a new product which does not imply f .

Definition 4.3 An irredundant sum-of-products expression (ISOP) is an SOP, where each product is a PI, and no product can be deleted without changing the function represented by the expression.

Definition 4.4 Let $f(X)$ be a function and p be a product of literal(s) in X . The restriction of f to p , denoted by $f(X|p)$ is obtained as follows: If x_i appears in p , then set x_i in 1 in f , and if \bar{x}_i appears in p , then set x_i in 0 in f .

Example 4.1 Let $f(x_1, x_2, x_3) = x_1x_2 \vee \bar{x}_2x_3$ and $p = x_1x_3$. $f(X|p)$ is obtained as follows: Set $x_1 = x_3 = 1$ in f , and we have $f(X|x_1x_3) = f(1, x_2, 1) = x_2 \vee \bar{x}_2 = 1$. (End of Example)

Lemma 4.1 p is an implicant of $f(X)$, iff $f(X|p) = 1$.

Example 4.2 By Lemma 4.1, x_1x_3 is an implicant of $x_1x_2 \vee \bar{x}_2x_3$, shown in Example 4.1. (End of Example)

Theorem 4.1 (OR type disjoint bi-decomposition) f has a disjoint bi-decomposition of form $f(X_1, X_2) = g_1(X_1) \vee g_2(X_2)$ iff every product in an ISOP for f consists of literals from X_1 only or X_2 only.

Definition 4.5 $x^0 = \bar{x}$. $x^1 = x$.

Corollary 4.1 If $f(x_1, x_2, \dots, x_n)$ has a PI of the form $x_1^{a_1}x_2^{a_2}\dots x_n^{a_n}$, where $a_i \in \{0, 1\}$, then f has no OR type disjoint bi-decomposition.

Let $x_i (i = 1, 2, \dots, n)$ be the input variables of f . Let $p_1 \vee p_2 \vee \dots \vee p_t$ be an irredundant sum-of-products expression for f , where $p_i (i = 1, 2, \dots, t)$ are PIs of f . Let Π_0 be the trivial partition of $\{1, 2, \dots, n\}$, $\Pi_0 = [\{1\}, \{2\}, \dots, \{n\}]$.

Algorithm 4.1 (OR type disjoint bi-decomposition: $f(X_1, X_2) = g_1(X_1) \vee g_2(X_2)$).

1. For $i = 1$ to t , form Π_i from Π_{i-1} by merging two blocks Ω_1 and Ω_2 of Π_{i-1} if at least one literal in p_i occurs in both Ω_1 and Ω_2 .
2. If Π_t has at least two blocks, then $f(X_1, X_2)$ has a disjoint bi-decomposition of the form $f(X_1, X_2) = g_1(X_1) \vee g_2(X_2)$, with X_1 the union of one or more blocks of Π_t and X_2 the union of the remaining blocks.

Example 4.3 Consider the ISOP: $f(x_1, x_2, \dots, x_6) = x_1x_2 \vee x_2x_3 \vee x_4x_5 \vee x_5x_6$. The products x_1x_2 and x_2x_3 show that x_1, x_2 , and x_3 are in the same block. Also, the products x_4x_5 and x_5x_6 show that x_4, x_5 , and x_6 are in the same block. Thus, we have the partition $[\{1, 2, 3\}, \{4, 5, 6\}]$. The corresponding OR type disjoint bi-decomposition is $f(X_1, X_2) = g_1(X_1) \vee g_2(X_2)$, where $X_1 = (x_1, x_2, x_3)$ and $X_2 = (x_4, x_5, x_6)$. (End of Example)

Example 4.4 Consider the function f with an ISOP: $f(x_1, x_2, x_3, x_4, x_5) = x_1x_2x_3 \vee x_3x_4x_5$.

- 1) The product $x_1x_2x_3$ shows that x_1, x_2 , and x_3 belong to the same block.
- 2) The product $x_3x_4x_5$ shows that x_3, x_4 , and x_5 belong to the same block.

Thus, all the variables belong to the same block. From this, it follows that f has no OR type decomposition. (End of Example)

Theorem 4.2 (AND type disjoint bi-decomposition) f has a disjoint bi-decomposition of form $f(X_1, X_2) = g_1(X_1)g_2(X_2)$ iff every product in an ISOP for f consists of literals from X_1 only or X_2 only.

Lemma 4.2 [14] An arbitrary n -variable function can be uniquely represented as

$$\begin{aligned}
 f(x_1, x_2, \dots, x_n) = & \\
 & a_0 \oplus (a_1x_1 \oplus a_2x_2 \oplus \dots \oplus a_nx_n) \\
 & \oplus (a_{12}x_1x_2 \oplus a_{13}x_1x_3 \oplus \dots \oplus a_{n-1n}x_{n-1}x_n) \\
 & \oplus \dots \oplus a_{12\dots n}x_1x_2\dots x_n, \quad (4.1)
 \end{aligned}$$

where $a_i \in \{0, 1\}$. The above expression is called a positive polarity Reed-Muller expression (PPRM).

For a given function f , the coefficients $a_0, a_1, a_2, \dots, a_{12\dots n}$ are uniquely determined. Thus, the PPRM is a canonical representation. The number of products in (4.1) is at most 2^n , and all the literals are positive (uncomplemented).

Theorem 4.3 (*EXOR type disjoint bi-decomposition*) f has a disjoint bi-decomposition of the form $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$ iff every product in the PPRM for f consists of literals from X_1 only or X_2 only.

Corollary 4.2 If the PPRM of an n -variable function has the product $x_1x_2\dots x_n$, then f has no EXOR type disjoint bi-decomposition.

Theorem 4.4 When f has an EXOR type disjoint bi-decomposition, the number of true minterms of f is an even number.

Corollary 4.3 When the number of true minterms of f is an odd number, then f does not have an EXOR type disjoint bi-decomposition.

The significance of this observation is that at least one half of the functions can be quickly rejected as candidates for EXOR type disjoint bi-decomposition.

Let x_i ($i = 1, 2, \dots, n$) be the input variables of f . Let $p_1 \oplus p_2 \oplus \dots \oplus p_t$ be PPRM for f , where p_i ($i = 1, 2, \dots, t$) are products. Let, Π_0 be the trivial partition of $\{1, 2, \dots, n\}$, $\Pi_0 = \{\{1\}, \{2\}, \dots, \{n\}\}$.

Algorithm 4.2 (*EXOR type disjoint bi-decomposition*): $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$.

1. For $i = 1$ to t , form Π_i from Π_{i-1} by merging two blocks Ω_1 and Ω_2 of Π_{i-1} if at least one literal in p_i occurs in both Ω_1 and Ω_2 .
2. If Π_i has at least two blocks, then $f(X_1, X_2)$ has a disjoint bi-decomposition of form $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$, with X_1 the union of one or more blocks of Π_i and X_2 the union of the remaining blocks.

Example 4.5 Consider the PPRM: $f(x_1, x_2, \dots, x_6) = x_1x_2 \oplus x_2x_3 \oplus x_4x_5 \oplus x_5x_6$. The products x_1x_2 and x_2x_3 show that x_1, x_2 , and x_3 are in the same block. Also, the products x_4x_5 and x_5x_6 show that x_4, x_5 , and x_6 are in the same block. Thus, we have the partition $\{\{1, 2, 3\}, \{4, 5, 6\}\}$. The corresponding EXOR type disjoint bi-decomposition is $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$, where $X_1 = (x_1, x_2, x_3)$ and $X_2 = (x_4, x_5, x_6)$. (End of Example)

Algorithm 4.3 (*Non-disjoint bi-decomposition*). $f(X_1, X_2, x_i) = g_1(X_1, x_i) \otimes g_2(X_2, x_i)$, where \otimes denotes either OR, AND, or EXOR. Let (X_1, X_2, x_i) be a partition of the variables x_1, x_2, \dots , and x_n . For $i = 1$ to n , do

- i) Let $f_{0i} = f(X_1, X_2, 0)$. (Set x_i to 0). Let $f_{1i} = f(X_1, X_2, 1)$. (Set x_i to 1).
- ii) If both f_{0i} and f_{1i} have the same type of disjoint bi-decompositions with the same partition, then f has a non-disjoint bi-decomposition.

V Complexity Analysis of the Algorithms

5.1 OR type disjoint bi-decomposition

We assume that the function is given as an ISOP with t products. Note that $t \leq 2^{n-1}$ [15]. The time to form the partition of variables is $O(n \cdot t)$.

5.2 EXOR type disjoint bi-decomposition

A PPRM can be represented by a functional decision diagram (FDD [5, 14]). Each path from the root node to the constant 1 node corresponds to a product in the PPRM. Thus, the partition of the input variables is directly generated from the FDD. The number of paths in an FDD is $O(2^n)$, where n is the number of the input variables. However, we can avoid exhaustive generation of paths as follows: Let p_1 and p_2 be products in a PPRM. If all the literals in p_1 also appear in p_2 , then p_2 need not be generated in the Algorithm, since the product p_1 that contains more literals than p_2 is more important. By searching the paths with more literals first, we can efficiently detect functions with no disjoint bi-decomposition.

Example 5.1 Consider the function $f(X)$ given as a PPRM: $f(X) = x_1 \oplus x_1x_2 \oplus x_3x_4 \oplus x_1x_2x_5x_6$. In constructing the partition of X , we need not consider the products x_1 or x_1x_2 , since $x_1x_2x_5x_6$ has the literals of x_1 and x_1x_2 . In this case, the product $x_1x_2x_5x_6$ shows that x_1, x_2, x_5 , and x_6 belong to the same group. Also, the product x_3x_4 shows that x_3 and x_4 belong to the same group. Thus, X is partitioned as $X = (X_1, X_2)$, where $X_1 = (x_1, x_2, x_5, x_6)$ and $X_2 = (x_3, x_4)$. (End of Example)

Definition 5.1 Let p be a product. The set of variables in p is denoted by

$$V(p) = \{x_i | x_i \text{ or } \bar{x}_i \text{ appears in } p\}.$$

For example, $V(x_1x_2\bar{x}_4) = \{x_1, x_2, x_4\}$

Definition 5.2 Let F be a PPRM. A product p is said to have maximal variable set $V(p)$ if there is no other product p' such that $V(p) \subset V(p')$.

Example 5.2 For the PPRM, $F = x_1x_2 \oplus x_1x_3 \oplus x_1x_2x_3 \oplus x_4$, $V(x_1x_2) = \{x_1, x_2\}$, $V(x_1x_3) = \{x_1, x_3\}$, $V(x_1x_2x_3) = \{x_1, x_2, x_3\}$, and $V(x_4) = \{x_4\}$. Thus, $x_1x_2x_3$ and x_4 have maximal variable sets. (End of Example)

Theorem 5.1 A function f has an EXOR type disjoint bi-decomposition if a function f' from the PPRM of f by eliminating implicants not having maximal variable sets has an EXOR type disjoint bi-decomposition.

The following theorem says that if a function has an EXOR type disjoint bi-decomposition, then the number of products in the PPRM is relatively small.

Theorem 5.2 If f has a disjoint bi-decomposition of the form $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$, then the number of products in the PPRM is at most $2^{n_1} + 2^{n_2} - 1$, where n_i is the number of variables in X_i ($i = 1, 2$).

VI Number of Functions with Bi-Decompositions

6.1 Functions with a small number of variables

In the previous sections, we showed that disjoint bi-decompositions are easy to find. In this section, we will enumerate the functions with disjoint bi-decompositions.

Definition 6.1 A function f is said to be nondegenerate if for all x_i , $f(\bar{x}_i) \neq f(x_i)$.

Definition 6.2 Two functions f and g are NP-equivalent, denoted by $f \stackrel{\text{NP}}{\sim} g$, iff g is derived from f by the following operations:

- 1) Permutation of the input variables.
- 2) Negations of the input variables.

The following is easy to prove.

Lemma 6.1 If f has a disjoint bi-decomposition and if $f \stackrel{\text{NP}}{\sim} g$, then g has also the same type of disjoint bi-decomposition.

Lemma 6.2 All the two-variable functions have disjoint bi-decompositions.

(Proof) The NP representative functions of two variables are x_1x_2 , $x_1 \vee x_2$, and $x_1 \oplus x_2$. All of them have disjoint bi-decompositions. ■

Example 6.1 There are $2^{2^3} = 256$ three-variable logic functions of which 218 are nondegenerate. These nondegenerate functions are grouped into 16 NP-equivalence classes as shown in Table 6.1 [8]. In this table, the column headed by N denotes the number of functions in that equivalence class. Eight classes have disjoint bi-decompositions, and three have non-disjoint bi-decompositions. Note that 146 functions have bi-decompositions. (End of Example)

The number of functions with AND type disjoint bi-decompositions is equal to the number of functions with OR type disjoint bi-decompositions.

In the case of disjoint bi-decompositions, a function has exactly one type of decomposition (Lemma 6.4). On the other hand, in the case of non-disjoint bi-decompositions, a function may have more than one type of bi-decompositions.

Example 6.2 Consider the three-variable function $f = \bar{x}_1x_3 \vee x_1x_2$. This function has three types of non-disjoint bi-decompositions:

$$\begin{aligned} f &= \bar{x}_1x_3 \vee x_1x_2 && \text{(OR type bi-decomposition)} \\ &= \bar{x}_1x_3 \oplus x_1x_2 && \text{(EXOR type bi-decomposition)} \\ &= (x_1 \vee x_3)(\bar{x}_1 \vee x_2) && \text{(AND type bi-decomposition)} \end{aligned}$$

(End of Example)

6.2 The number of functions with bi-decompositions

Harrison [4] has counted the number of nondegenerate functions. Specifically,

Lemma 6.3 [4]: Let $\alpha(n)$ be the number of nondegenerate functions on n variables. Then,

$$\alpha(n) = \sum_{k=0}^n \binom{n}{k} (-1)^{n-k} 2^{2^k} \sim 2^{2^n},$$

where $a(n) \sim b(n)$ means $\lim_{n \rightarrow \infty} \frac{a(n)}{b(n)} = 1$.

Lemma 6.4 A nondegenerate function f has at most one type of disjoint bi-decomposition:

1. $f(X_1, X_2) = g_1(X_1) \cdot g_2(X_2)$,
2. $f(X_1, X_2) = g_1(X_1) + g_2(X_2)$, or
3. $f(X_1, X_2) = g_1(X_1) \oplus g_2(X_2)$,

where g_1 and g_2 are nondegenerate functions on one or more variables.

Theorem 6.1 The number of functions $N_{\text{disjoint}}(n)$ with disjoint bi-decompositions is

Table 6.1: NP-representative functions of three variables.

	Representative functions	N	Type	Property
1	$x_1 \oplus x_2 \oplus x_3$	2	EXOR	Disjoint
2	$x_1 x_2 x_3$	8	AND	Bi-Decomposition
3	$x_1 \vee x_2 \vee x_3$	8	OR	
4	$x_1(x_2 \vee x_3)$	24	AND	
5	$x_1 \vee x_2 x_3$	24	OR	
6	$x_1(x_2 \oplus x_3)$	12	AND	
7	$x_1 \vee (x_2 \oplus x_3)$	12	OR	
8	$x_1 \oplus x_2 x_3$	24	EXOR	
9	$x_1 x_2 x_3 \vee \bar{x}_1 \bar{x}_2 \bar{x}_3$	4		
10	$(x_1 \vee x_2 \vee x_3)(\bar{x}_1 \vee \bar{x}_2 \vee \bar{x}_3)$	4		
11	$\bar{x}_1 x_3 \vee x_1 x_2$	24		
12	$x_1 \bar{x}_2 \bar{x}_3 \vee x_2 x_3$	24		No Bi-Decomposition
13	$(x_1 \vee \bar{x}_2 \vee \bar{x}_3)(x_2 \vee x_3)$	24		
14	$x_1 x_2 \vee x_2 x_3 \vee x_3 x_1$	8		
15	$x_1 x_2 \vee x_2 x_3 \vee x_1 x_3 \vee \bar{x}_1 \bar{x}_2 \bar{x}_3$	8		
16	$\bar{x}_1 x_2 x_3 \vee x_1 \bar{x}_2 x_3 \vee x_1 x_2 \bar{x}_3$	8		

N : Number of the functions in the class.

Table 6.2: Number of functions.

		$n = 2$	$n = 3$	$n = 4$
All the functions		16	256	65536
Nondegenerate functions		10	218	64594
Functions with bi-decomposition	Disjoint	4	44	1660
	AND	4	44	1660
	OR	2	26	914
	EXOR	2	26	914
Non-disjoint		0	32	3860
Total		10	146	8094

$N_{disjoint}(n) = A_{dis}(n) + O_{dis}(n) + E_{dis}(n)$, where

$$A_{dis}(n) = n! \sum_{\substack{k_1, k_2, \dots, k_n \geq 0 \\ 1k_1 + 2k_2 + \dots + nk_n = n}} \prod_{i=1}^n \left(\frac{\alpha(i) - A_{dis}(i)}{i!} \right)^{k_i} \frac{1}{k_i!}$$

$$O_{dis}(n) = n! \sum_{\substack{k_1, k_2, \dots, k_n \geq 0 \\ 1k_1 + 2k_2 + \dots + nk_n = n}} \prod_{i=1}^n \left(\frac{\alpha(i) - O_{dis}(i)}{i!} \right)^{k_i} \frac{1}{k_i!}$$

$$E_{dis}(n) = 2n! \sum_{\substack{k_1, k_2, \dots, k_n \geq 0 \\ 1k_1 + 2k_2 + \dots + nk_n = n}} \prod_{i=1}^n \left(\frac{\alpha(i) - E_{dis}(i)}{i!} \right)^{k_i} \frac{1}{2^{k_i} k_i!}$$

where the sums are over all partitions of n except the trivial partition $n = 0 \cdot 1 + 0 \cdot 2 + \dots + 0 \cdot (n-1) + 1 \cdot n$ (i.e. the sum is over all partitions where $k_n = 0$), and where $A_{dis}(1) = O_{dis}(1) = E_{dis}(1) = 0$.

Table 6.2 shows the number of functions with disjoint bi-decompositions up to $n = 4$.

VII Representations of Functions with Disjoint Bi-Decompositions

7.1 Expressions for the functions with bi-decomposition

Definition 7.1 A logical sum that contains at most one literal for each variable is called a sum term. Sum terms combined with AND operators form a product-of-sums (POS).

Definition 7.2 Among the SOPs for f , the one with the minimum number of products is a minimal SOP (MSOP). Among the POSs for f , the one with the minimum number of sum terms is a minimal POS (MPOS).

Definition 7.3 The number of products in the sum-of-products expression G is denoted by $\tau(G)$. The number of products in an MSOP for f is denoted by $\tau(\text{MSOP} : f)$. The number of sum terms in MPOS for f is denoted by $\tau(\text{MPOS} : f)$.

Theorem 7.1 Let f have an OR type disjoint bi-decomposition: $f(X, Y) = g(X) \vee h(Y)$. Let $G_m(X)$, and $H_m(Y)$ be MSOPs for g and h , respectively. Then $G_m(X) \vee H_m(Y)$ is an MSOP for h .

Also, $\tau(MSOP : f) = \tau(MSOP : g) + \tau(MSOP : h)$.

Corollary 7.1 *Let f have an AND type disjoint bi-decomposition: $f(X, Y) = g(X)h(Y)$. Let $G_m(X)$ and $H_m(Y)$ be MPOSs for g and h , respectively. Then, $G_m(X)H_m(Y)$ is an MPOS for f . Also, $\pi(MPOS : f) = \pi(MPOS : g) + \pi(MPOS : h)$.*

Theorem 7.1 and Corollary 7.1 shows that if f has an OR (AND) type disjoint decomposition, then the minimum expressions can be obtained by minimizing sub-functions independently.

7.2 BDDs for the functions with bi-decomposition

Definition 7.4 *Let $N(BDD : f)$ denote the number of non-terminal nodes for f , for a given order of input variables.*

Theorem 7.2 *If f has a disjoint bi-decomposition of form $f(X_1, X_2) = h(g_1(X_1), g_2(X_2))$ and if h is a unate function, then the BDD for f is represented with $N(BDD : g_1(X_1)) + BDD : N(g_2(X_2))$ nodes.*

Theorem 7.3 *If f has a disjoint bi-decomposition of form $f(X_1, X_2) = h(g_1(X_1), g_2(X_2))$ and if h is a non-unate function, then $N(BDD : f) = N(BDD : g_1(X_1)) + N(BDD : g_2(X_2)) + \min\{N(BDD : g_1(X_1)), N(BDD : g_2(X_2))\}$.*

VIII Conclusions and Comments

In this paper, we presented the bi-decomposition, a special case of functional decomposition. Disjoint bi-decompositions have the following features:

- 1) They are easy to detect; we use ISOPs or PPRMs rather than decomposition charts.
- 2) If the function has an OR (AND) type bi-decomposition, then we can optimize the expression separately.
- 3) Programmable logic devices exist that realize bi-decompositions.

We enumerated functions with bi-decompositions. Among 218 nondegenerate functions of 4 variables, 146 have bi-decompositions. Also, we derived formulae for the number of disjoint bi-decompositions.

Since the fraction of functions with decompositions approaches to zero as n increase [4], the fraction of functions with bi-decompositions also approaches to zero as n increases. Future problems include the investigation of benchmark functions with bi-decomposition.

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