# Wide-area Group Communication \*

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### 1 Introduction

Distributed systems are composed of multiple computers interconnected by communication networks. In distributed applications like teleconferences, a group of multiple processes is established and the processes in the group are cooperated. Group communication protocols support a group of processes with the reliable and ordered delivery of messages to multiple destinations. Group communication protocols discussed so far assume that every pair of processes have almost the same delay time and reliability. In the Internet, it takes about 60 msec to propagate a message in Japan while taking about 240 msec between Tokyo and Europe. In addition, the longer the distance is, the more messages are lost. For example, about 20% of the messages are lost between Japan and Europe while less than 1% are lost in Japan. Thus, it is essential to consider a group communication where the delay times between the processes are significantly different [1], i.e. not neglectable compared with the processing speed. Such a group of processes is named a wide-area group. In the wide-area group, the time for delivering messages to the destinations is dominated by the longest delay between the processes.

## 2 System Model

A communication system is composed of three hierarchical layers, i.e. application, transport, and network layers. A group of  $n \geq 2$  application processes  $AP_1, \ldots, AP_n$  are cooperated. Each  $AP_i$  communicates with other processes in the group by using the underlying group communication service provided by transport processes  $TP_1, \ldots, TP_n$ . Here, let G be a group of the transport processes  $(G = \{TP_1, \ldots, TP_n\})$ . The network layer provides the IP service for the transport layer. A transport process  $TP_i$  requests the network layer to transmit ICMP "Timestamp" packets to know the delay time with each  $TP_i$  in G. We make the following assumptions about packets sent by  $TP_i$ : Packets may be lost and duplicated. Packets sent by the same process may be received by the destination processes not in the sending order.

# 3 Reliable Receipt

#### 3.1 Transmission and confirmation

In the group communication, a message m sent by one process  $TP_i$  is sent to multiple destination processes in a group G. m has to be reliably delivered to all the destinations in G. There are two points to be discussed to realize the reliable receipt of m:

- (1) how to deliver m to the destinations of m, and
- (2) how to deliver the receipt confirmation of m to the sender  $TP_i$  and the destinations.

In (1), there are two ways: direct and hierarchical ones. In the direct multicast,  $TP_i$  sends m directly to

all the destinations. In the hierarchical multicast,  $TP_i$  sends m to a subset of the destinations. On receipt of m from  $TP_i$ ,  $TP_j$  forwards m to other destinations.

In (2), there are two schemes to deliver the confirmation: decentralized and distributed ones. In the decentralized scheme,  $TP_i$  sends m to the destinations and the destinations send back the receipt confirmation of m to  $TP_i$ . If  $TP_i$  receives all the confirmations,  $TP_i$  informs all the destinations of the reliable receipt of m. In the distributed scheme [2], every destination  $TP_j$  sends the receipt confirmation of m to all the destinations and  $TP_i$  on receipt of m. If each  $TP_j$  receives the confirmations from all the destinations,  $TP_j$  reliably receives m.

## 3.2 Recovery from message loss

In the underlying network, messages are lost due to buffer overruns, unexpected delay, and congestion. Hence, the processes have to recover from the message loss. There are two ways to retransmit m if  $TP_j$  loses m sent by  $TP_i$ . (1) Sender retransmission:  $TP_i$  retransmits m to  $TP_j$ . (2) Destination retransmission: some destination process  $TP_k$  forwards m to  $TP_j$ .

### 3.3 Protocols

Suppose that a process  $TP_i$  sends m to a subset  $V_m$  of the destination processes in the group G. There are the following protocols.

- (1) Basic (B) protocol: direct multicast and distributed confirmation with sender retransmission.
- (2) Modified (M) protocol: direct multicast and distributed confirmation with destination retransmission.
- (3) Nested group (N) protocol: hierarchical multicast and decentralized confirmation with destination retransmission.
- (4) Decentralized (D) protocol: direct multicast and decentralized confirmation with sender retransmission.

### [Basic (B) protocol]

- (T1)  $TP_i$  sends m to every destination process in  $V_m$ .
- (T2) On receipt of m, each process  $TP_j$  in  $V_m$  sends the receipt confirmation to  $TP_i$ .
- (T3) On receipt of the confirmation messages from all the processes in  $V_m$ ,  $TP_i$  reliably receives m.
- (R) If some  $TP_j$  fails to receive m,  $TP_i$  sends m to  $TP_j$  again.  $\square$

The modified (M) protocol is the same as B except that the destination retransmission is adopted.

#### [Modified (M) protocol]

(R) If  $TP_j$  fails to receive m, some destination  $TP_k$  nearest to  $TP_j$  sends m to  $TP_j$ . If all the destinations lose m, T1 is executed again.  $\square$ 

In the N protocol, G is decomposed into disjoint subgroups  $G_1, ..., G_{sg}$   $(sg \ge 2)$ . Each  $G_i$  is composed of the processes  $TP_{i1}, ..., TP_{ih_i}$   $(h_i \ge 1)$  where  $TP_{i1}$ 

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is a coordinator.

## [Nested group (N) protocol]

- (T1)  $TP_{ij}$  sends m to the coordinator  $TP_{i1}$ . Let  $DC_i$  be a set of the coordinators whose subgroups include the destinations of m.  $TP_{i1}$  forwards m to the coordinators in  $DC_i$ .
- (T2) On receipt of m, the coordinator  $TP_{k1}$  sends m to the destinations in  $G_k$ . On receipt of m, the destination  $TP_{kh}$  sends the confirmation back to  $TP_{k1}$ . On receipt of the confirmations from all the destinations in  $G_k$ ,  $TP_{k1}$  sends the confirmation to the coordinators in  $DC_i$ .
- (T3) On receipt of the confirmations from all coordinators in  $DC_i$ ,  $TP_{k1}$  sends the confirmation to the destinations in  $G_k$ . On receipt of the confirmation from  $TP_{k1}$ ,  $TP_{kh}$  reliably receives m.
- (R) If  $TP_{kh}$  fails to receive m,  $TP_{k1}$  resends m to  $TP_{kh}$ .  $\square$

In the D protocol, only the sender  $TP_i$  can know whether each destination receives m or not. T1 and R are the same as the B protocol.

### [Decentralized (D) protocol]

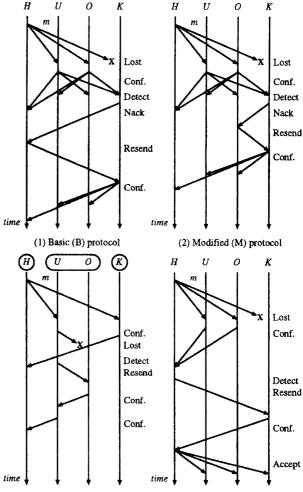
- (T2) On receipt of m,  $TP_j$  sends the confirmation back to  $TP_i$ .
- (T3) On receipt of all the confirmations,  $TP_i$  sends the acceptance to all the processes in B.
- (T4) On receipt of the acceptance,  $TP_i$  accepts m.  $\square$

#### 4 Evaluation of Protocols

We evaluate the four protocols in terms of the delay time for delivering and reliably receiving messages. The prototypes of the protocols have been implemented to be a group G of seven UNIX processes in SPARC workstations, i.e. three in Hatoyama, one in Tokyo, Japan, two in the U.S. and one in Keele, UK. We consider two cases: (1) there is no message loss and (2) some processes lose m. We measure the delay time where a process in UK sends a message m of 128 bytes to three processes in Hatoyama. In the N protocol, G is composed of Keele and Hatoyama subgroups. The following kinds of delays are obtained from the times measured: receipt(R) delay = time(receive) - time(send), delivery(DL) delay = time(deliver) - time(send), reliable receipt(RR) delay = time(reliable receive) - time(send), and detect(DT) delay = time(detect) - time(send).

- (1) of Table 1 indicates the R, DL, and RR delays for four protocols in the first case. The difference between R and DL shows time for the protocol processing. The difference between R and RR shows time for exchanging the confirmation messages of m. Every protocol supports almost the same delay.
- (2) of Table 1 shows the R, DT, DL, and RR delays in the presence of lost messages. The difference between DL and DT shows time for recovering from the message loss by retransmission. In the N protocol, we consider two cases: messages are lost among coordinators and lost in subgroups. The delay times in the first case are marked \* in Table 1.

Following Table 1, the processes can recover from message loss with shorter delay in the M protocol than the others. In the wide-area group, each channel is different in the delay time and message loss ratio. Hence, the messages can be delivered with shorter delay if the messages are sent through channels with the shorter delay and less loss ratio.



(3) Nested group (N) protocol

(4) Decentralized (D) protocol

Figure 1: Protocols

#### 5 Concluding Remarks

We have discussed the wide-area group communication which includes multiple processes interconnected by the Internet. Here, each logical channel between the processes in the group has a different delay time and message loss ratio. In this paper, we have presented ways to reduce the delay time of messages in the wide-area group.

Table 1: Delay [msec]

	Protocols	В	M	N	D
(1)	receipt(R)	376	376	377	376
	delivery(DL)	383	383	384	383
	rel. rec. (RR)	724	724	726	1128
	detect (DT)	386	386	387 726*	762
(2)	receipt (R)	1140	393	394 1103*	1135
	delivery (DL)	1141	394	395 1105*	1139
	rel. rec. (RR)	1527	735	736 1482*	1891

#### References

- [1] Hofmann, M., Braun, T., and Carle, G., "Multicast Communication in Large Scale Netwoks,"

  Third IEEE Workshop on High Performance
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- [2] Nakamura, A. and Takizawa, M., "Causally Ordering Broadcast Protocol," Proc. of IEEE ICDCS-14, 1994, pp.48-55.