

On  $k$ -component Algorithms for Graphs and Digraphs.

2D-5

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## 1. Introduction.

Consider a digraph (or graph)  $G$  without any self-loops or parallel-edges. We denote the vertex-set and edge-set of  $G$  by  $V(G)$  and  $E(G)$ , respectively. We denote the cardinality of  $V(G)$  and  $E(G)$ , namely,  $|V(G)|$  or  $|E(G)|$  by  $n$  and  $e$ , respectively.  $G$  is  $k$ -connected, if there exist at least  $k$  vertex-disjoint paths from  $v$  to  $w$ , for every ordered pair of  $v$  and  $w$  ( $v, w \in V(G)$ ). A  $k$ -component of  $G$  is a maximal  $k$ -connected subgraph of  $G$  (see Figure 1).

Hopcroft and Tarjan discovered algorithms for finding 1-components, 2-components and 3-components of a graph, as well as 1-components of a digraph, within  $O(n+e)$  time [Ta72], [HoTa73]. The existence of such linear algorithms for finding  $k$ -components of a graph for any fixed  $k$  ( $> 3$ ) was conjectured in [AhHoU174]; however, no such linear algorithm has been found. Recently, Kanevsky and Ramachandran discovered an algorithm that finds all separating triplets of a 3-connected graph in  $O(n^2)$  time [KaRa87], which suggests the existence of an efficient algorithm for finding 4-components of a graph; however, finding all separating triplets does not directly yield a decomposition into 4-components, and the problem still remains.

Matula discovered a polynomial algorithm that finds all the  $k$ -components of a graph, using cluster analysis techniques [Ma77]. Note that the problems for graphs are easily reducible to those for symmetrical digraphs, although the converse is not true. Our purpose is to construct an algorithm to find all the  $k$ -components of a digraph. Our algorithm can be regarded as an extension and refinement (a practical, and probably more efficient version) of Matula's.

Proceeding to our main results, we need to introduce some notations. For  $v, w \in V$ , let  $[v, w]$  denote a directed edge which leaves  $v$  and enters  $w$ . For  $v \in V$ , let  $\Gamma^+(v) = \{w \mid [v, w] \in E(G)\}$ , and  $\Gamma^-(v) = \{w \mid [w, v] \in E(G)\}$ . We denote  $\deg(v) = \min\{|\Gamma^+(v)|, |\Gamma^-(v)|\}$ .  $G$  is complete if  $\Gamma^+(v) = \Gamma^-(v) = n - 1$ , for  $\forall v \in V(G)$ . For  $U \subset V(G)$ ,  $\ll U \gg_G$  denotes the induced subgraph of  $G$  by  $U$ , that is, a subgraph of  $G$  whose vertex-set is  $U$ , and whose edge-set is  $\{[v, w] \in E(G) \mid v, w \in U\}$ .  $S \subset V(G)$  is a separator of  $G$  if  $\ll V(G) \setminus S \gg_G$  is not 1-connected. For  $l \geq 1$ , a  $l$ -separator, denoted by  $\xi^l(G)$ , is a

minimum separator,  $S$ , of  $G$ , such that  $|S| \leq l$ . Note that  $\xi^l(G)$  is nothing but a minimum separator of  $G$ , if it exists, and that otherwise  $\xi^l(G)$  is empty (see Figure 1). We assume all digraphs in our algorithm are represented by adjacency structures [AhHoU174], [Ta72], and manipulated in an efficient way. Our results are summarized as follows.

**Theorem 1** *Let  $G$  be a digraph with  $n$  vertices and  $e$  edges. All the possible  $v$ -components ( $k \leq v \leq l$ ) of  $G$  are found within  $O((n-k) \times \text{Max}\{n+e, T_l\})$  time, where  $T_l$  is the time bound for computing  $\xi^l(G)$ .*

Many algorithm are available for computing  $\xi^l(G)$  for digraphs [EvTa75], [Ga80]. In particular, Galil's approach [Ga80] yields an  $O(l \times (n+e) \times \sqrt{n} \times \text{Max}\{l, \sqrt{n}\})$  time algorithm for computing  $\xi^l(G)$ . Thus we have:

**Corollary 1** *All the possible  $v$ -components ( $k \leq v \leq l$ ) of a digraph  $G$  are found within  $O((n-k) \times l \times (n+e) \times \sqrt{n} \times \text{Max}\{l, \sqrt{n}\})$  time.*

Provided that  $G$  is a symmetrical digraph, or a graph, we can use more efficient algorithms for computing  $\xi^l(G)$ , [EsHa84], [GrHa86]. Combining Granot-Hassin's algorithm [GrHa86] with Even-Tarjan's maximum-flow algorithm [EvTa75], we can compute  $\xi^l(G)$  in  $O(n \times (n+e) \times \min\{l, \sqrt{n}\})$  time. Thus we have:

**Corollary 2** *All the possible  $v$ -components ( $k \leq v \leq l$ ) of a symmetrical digraph (or graph)  $G$  are found within  $O((n-k) \times n \times (n+e) \times \min\{l, \sqrt{n}\})$  time.*

Note that Corollary 1 and Corollary 2 show the same time bound, if  $l \leq \sqrt{n}$ . In particular, combined with Kanevsky-Ramachandran and Hopcroft-Tarjan algorithms [KaRa87], [HoTa73], Theorem 1 yields an  $O(n^3)$  bound for finding 4-components of a graph.

## 2. Proof of Theorem 1.

The proof of Theorem 1 is essentially the same as that shown in [M88].

### 3. Algorithm.

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1. procedure FMC(k,l,G)
2. begin if k ≤ l then
3.   begin if |V(G)| ≥ k + 1 then
4.     repeat
5.       for ∀v ∈ V(G) do
6.         if deg(v) < k then
7.           eliminate v, together with
8.             Γ+(v), and Γ-(v) from G;
9.         find 1-components of G;
10.        eliminate all edges linking between
11.          any two 1-components from G;
12.        until
13.          |V(G)| < k + 1, or min{deg(v)|v ∈ V(G)} ≥ k;
14.        if |V(G)| = k + 1 and G is complete then
15.          output G as a k-component;
16.        if |V(G)| > k + 1 then
17.          for each 1-component Gi of G do
18.            begin find ξ(Gi);
19.            if ξ(Gi) is empty then
20.              output Gi as a (l + 1)-component;
21.            else if |ξ(Gi)| ≥ k then
22.              begin output a copy of Gi
23.                as a |ξ(Gi)|-component;
24.                Gi ← ⋖V(Gi) \ ξ(Gi)⋗Gi;
25.                find 1-components of Gi;
26.                eliminate all edges linking between
27.                  any two 1-components from Gi;
28.                k' ← Max{k, |ξ(Gi)| + 1};
29.                for each 1-component Pj of Gi do
30.                  begin Let Gj' ← ⋖V(Pj) ∪ ξ(Gi)⋗Gi;
31.                    FMC(k', l, Gj');
32.                  end;
33.                end;
34.            end;
35.          end;
36.        end;
37.      end;
38.    end;
39.  end;
40. end;

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### 4. Remarks.

In our algorithm, degree checks and eliminations of unavailable edges in lines 4 - 8 are not necessary to achieve the time bounds of section 1. However, in many cases, these simple tricks yield considerable reduction of the cost, while the precise estimation still remains.

### 5. References.

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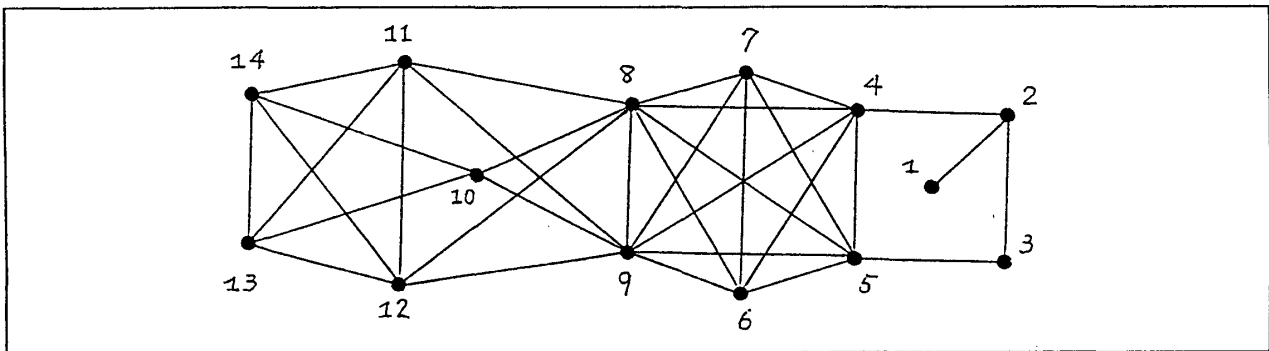


Figure 1. A graph  $G$  with 14 vertices.  $G$  itself is the 1-component. 2-component is  $\llbracket 2, 3, \dots, 14 \rrbracket_G$ , 3-component is  $\llbracket 4, 5, \dots, 14 \rrbracket_G$ , 4 and 5-component is  $\llbracket 4, 5, \dots, 9 \rrbracket_G$ .  $\xi^4(\llbracket 4, 5, \dots, 14 \rrbracket_G)$  is  $\{8, 9, 10\}$ .  $\xi^2(\llbracket 4, 5, \dots, 14 \rrbracket_G)$  is empty.