

A Compact Encoding of Rooted Trees

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In this paper, we give compact codes for (unordered) rooted trees. We show that the codes are compact experimentally. For instance, the code occupies $1.556n$ bits per a rooted tree with $n = 24$ vertices on average. While an ordered tree of n vertices is encoded with $2n$ bits, which coincide with the information-theoretically optimal bound, our scheme is more compact.

1. Introduction

Trees are one of most important structures in computer science, and frequently used as models in various areas including searching, program parsing and mining semi-structured data such as XML. These days, we face a huge tree structure.

In this paper we focus on a compact representation of an unordered tree. We design a binary code that represents an unordered tree compactly.

For some class C , how many bits are needed to encode an element in C into a binary string S so that S can be decoded to reconstruct the original element? For any coding scheme the average length of S is at most $\log |C|^{*1}$ bits, which is called the *information-theoretically optimal bound*.

The number of ordered trees with n vertices is about $c_1 2^n / n^{\frac{3}{2}}$, e.g. [10], where $c_1 = 1/4\sqrt{\pi} \approx 0.1410$. Hence the information-theoretically optimal bound is $2n$ bits (ignoring logarithmic terms). The number of rooted unordered trees with n vertices is about $c_2 \alpha^n / n^{\frac{3}{2}}$, e.g. [10], where $c_2 = 0.5350$ and $\alpha \approx 2.9558$. Hence, the information-theoretically optimal bound is $1.564n$ bits asymptotically (ignoring logarithmic terms).

For ordered trees, there are many results on compact representations [1, 4, 6, 7]. For free trees, Farzan and Munro [3] proposed a succinct representation taking

$1.564n + o(n)$ bits, where n is the number of vertices. Their method can be applied for rooted trees by specifying the root vertex with $\log n$ bits. The representation attains information-theoretically optimal bound by using auxiliary tables with $o(n)$ space. Their result is theoretically nice, however the size of the tables would be huge.

On the other hand, for unordered-rooted binary tree with n vertices, Iwata et al.[5] proposed a compact code with $1.4n + 4$ bits without an auxiliary table. The information-theoretically optimal bound for such trees is $1.312n$ bits [2, 11]. Their result is near to the optimal length.

Is there a coding scheme for rooted trees which attains information-theoretically optimal bound without an auxiliary table? In this paper, we design a coding method for rooted trees with n vertices without an auxiliary table. We experimentally show that an average length of our code is compact. For the case of $n = 24$, our method encodes a rooted trees into $1.556n$ bits per a rooted tree on average.

2. Definitions

In this section, we give some definitions.

Let G be a connected graph with n vertices. A *path* is a sequence of distinct vertices (v_1, v_2, \dots, v_p) such that (v_{i-1}, v_i) is an edge for $i = 2, 3, \dots, p$. The *length* of a path is the number of edges in the path.

A *tree* is a connected graph with no cycle. A *rooted tree* is a tree with one vertex r chosen as its *root* vertex. For each vertex v in a rooted tree, let $UP(v)$ be the unique path from v to r . The *parent* of $v \neq r$ is its neighbour on $UP(v)$, and the *ancestors* of $v \neq r$ are the vertices on $UP(v)$ except v . The parent of r and the ancestors of r are not defined. We say if v is the parent of u then u is a *child* of v , and if v is an *ancestor* of u then u is a *descendant* of v . A *leaf* is a vertex having no child. If a vertex is not a leaf, then it is called an *inner* vertex. The *degree* of a vertex v , denoted by $d(v)$, is the number of children of v .

An *ordered tree* is a rooted tree with a left-to-right ordering specified for the children of each vertex. We denote by $T(v)$ the subtree of an ordered tree T consisting of a vertex v and all descendants of v that preserve the left-to-right ordering for the children of each vertex. Let $CS(v) = (c_1, c_2, \dots, c_{d(v)})$ be the

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*1 Log denotes logarithm to the base 2

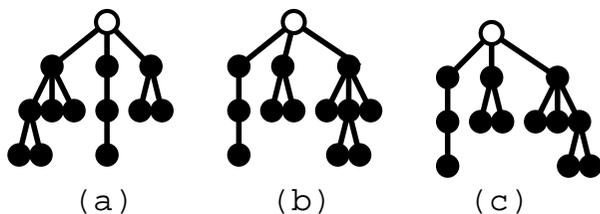


Fig. 1 Three different ordered trees which are isomorphic as rooted tree.

sequence of the children of v from left-to-right. We call it the *child sequence* of v . Each c_i is called the *next sibling* of c_{i-1} for $i = 2, 3, \dots, d(v)$ and the *previous sibling* of c_{i+1} for $i = 1, 2, \dots, d(v) - 1$. Three trees in Fig. 1 are different ordered trees, but are isomorphic as rooted trees.

3. Depth-first Unary Degree Sequence

In this section we briefly introduce a DFUDS (Depth-First Unary Degree Sequence) for an ordered tree [1]. DFUDS is a binary code for an ordered tree. It can represent an ordered tree with n vertices in $2n - 1$ bits

Let T be an ordered tree with n vertices, and v be a vertex of T . We define a block for v as follows. A *block*, denoted by $B(v)$, for v is $d(v)$ consecutive ‘0’s followed by one ‘1’. We traverse T with depth-first manner. If we visit v first, then output $B(v)$. The obtained binary code is *DFUDS* for T . DFUDS consists of n blocks. The length of DFUDS is $2n - 1$ bits, For instance, DFUDS for the tree in Fig. 1(a) is 00010001001110101100111.

Decoding for DFUDS is a simple algorithm based on depth-first search of a tree using a stack. Here we carefully explain decoding for DFUDS, since it helps to understand how to decode our code explained later (Section 5).

Let S_1 be a DFUDS for an ordered tree. The first zero or more ‘0’s followed by one ‘1’ consist of the block for the root vertex r . By reading the first block, we know the degree $d(r)$. For the block, we create a new vertex for r , then we push $d(r)$ copies of r to a stack. Now, we explain how to decode vertices except r . We reconstruct each vertex in preorder. First we read a block $B(v)$ consisting of $d(v)$ ‘0’s followed by one ‘1’. Second we create a new vertex for v , then connect v to the vertex popped from the stack as the parent of v . Finally we push $d(v)$

copies of v into the stack. We repeat this process for each vertex in preorder.

4. Canonical Representation of Rooted Trees

Let R be a rooted tree. We can observe that R corresponds to many non-isomorphic ordered trees, since we can choose many left-to-right orderings for the children of each vertex in T . If we uniquely define a “canonical” ordered tree among ordered trees corresponding to R , then encoding canonical ordered trees means an algorithm that encodes rooted trees. This idea is also adopted for enumerating some classes of trees [8, 9]. However how to choose a canonical tree is slightly different from our method.

Let T be an ordered tree with n vertices, and (v_1, v_2, \dots, v_n) be the list of the vertices of T in preorder. Then, a sequence $DF(T) = (d(v_1), d(v_2), \dots, d(v_n))$ is called the *DF degree sequence* of T . Let T_1 and T_2 be two ordered trees, and $DF(T_1) = (a_1, a_2, \dots, a_n)$ and $DF(T_2) = (b_1, b_2, \dots, b_m)$ be their DF degree sequences. If either (1) $a_i = b_i$ for each $i = 1, 2, \dots, j - 1$ and $a_j < b_j$, or (2) $a_i = b_i$ for each $i = 1, \dots, n$ and $n < m$, then we say that T_1 is *smaller* than T_2 , and write $T_1 \prec T_2$.

For example, DF degree sequences of trees in Figs. 1(a), (b) and (c) are $(3, 3, 2, 0, 0, 0, 0, 1, 1, 0, 2, 0, 0)$, $(3, 1, 1, 0, 2, 0, 0, 3, 0, 2, 0, 0, 0)$ and $(3, 1, 1, 0, 2, 0, 0, 3, 0, 0, 2, 0, 0)$, respectively.

Now, we define a canonical representation of R as follows. The ordered tree T is a *canonical tree* of R if (1) T is isomorphic to R as a rooted tree and (2) $DF(T)$ is smallest among all ordered trees corresponding to R . For example, the ordered tree in Fig. 1(c) is the canonical tree, however the trees in Figs. 1(a) and (b) are not.

We have the following two lemmas.

Lemma 4.1 The canonical tree of a rooted tree is unique.

Lemma 4.2 Let T be a canonical tree and $CS(v) = (c_1, c_2, \dots, c_{d(v)})$ be the child sequence for any inner vertex v of T . Then we have $d(c_i) \leq d(c_{i+1})$ for $i = 1, 2, \dots, d(v) - 1$.

Proof. We assume otherwise for a contradiction. Let (v_1, v_2, \dots, v_n) be the sequence of vertices of T in preorder. We choose the minimum i such that $CS(v_i)$ destroys the above condition. More precisely, i is the minimum ($1 \leq i \leq n$) such

that $d(c_j) > d(c_{j+1})$ holds for some j in $CS(v_i)$. If we exchange c_j and c_{j+1} , then we obtain a smaller tree than T , which is a contradiction. \square

We also have the following lemma.

Lemma 4.3 An ordered tree T is canonical tree if $T(u) \prec T(v)$ or $T(u) \cong T(v)$ for every u and its next sibling v .

Proof. By contradiction. \square

5. Compact Codings and Decodings

In this section we design compact codes for a rooted tree. Our idea is to encode the canonical tree of a rooted tree. If we encode the canonical tree of a rooted tree, then it also means that we can encode a rooted tree by Lemma 4.1. Given a rooted tree R , we construct a canonical tree T of R , then we encode a canonical tree with a binary code. The obtained code is the code for R .

Our encoding method is based on DFUDS for an ordered tree. By modifying DFUDS, we design a compact code for a canonical tree. In this section, we introduce three ideas for improvements. From now on, we denote by S_1 DFUDS for T .

Difference

The first idea for improvements is to store the number of children of each vertex as a difference from its previous sibling. Let u, v be a vertex and its previous sibling. A *difference block* $D(u)$ is equal to $B(u)$ if u is the first child of its parent, and $D(u)$ is a code consisting of $d(u) - d(v)$ ‘0’s followed by ‘1’ if u is not the first child of its parent. We define S_2 a binary code obtained by arranging all difference blocks in preorder of vertices.

Decoding the original rooted tree from S_2 is almost same as decoding of DFUDS. If the first i vertices in preorder are decoded, then we can compute $d(v_{i+1})$ from $D(v_{i+1})$, which is $(i + 1)$ th block in S_2 , and the degree of the previous sibling of v_{i+1} . Therefore we can decode S_2 .

Now we estimate the length of S_2 . Clearly we have $|S_0| \leq |S_1|$. Are there trees that satisfy $|S_0| = |S_1|$? For instance, if T is a path, S_2 needs $2n - 1$ bits. So we can observe that, if T includes many paths as its subgraphs, then $|S_2|$ comes up to $|S_1|$. From this observation, we have an idea which is to compress path

structures in a tree ^{*1}.

Path Compression

We give a formal definition of subpath. Let (v_1, v_2, \dots, v_n) , $(v_1 \neq r)$, be the sequence of vertices of T in preorder. A maximal subgraph induced by consecutive vertices v_i, v_{i+1}, \dots, v_j ($i \leq j$) is an *inner subpath* if $d(v_k) = 1$ for $k = i, i+1, \dots, j$.

During a depth-first search of T , if the current v has one child and the parent of v is not (or v is the root vertex with degree 1), then v may be the start vertex of an inner subpath in T . For such vertex, we store the length of the path starting from the child of v (or v) by an unary code.

Now we explain our coding more formally. Assume that v_i, v_{i+1}, \dots, v_j consist an inner subpath. After $D(v_i)$, we encode a subpath v_{i+1}, \dots, v_j of the inner subpath with $j - i$ ‘0’s followed by one ‘1’.

We can observe that v_{j+1} is a leaf or has two or more children. Then we encode v_{j+1} with ‘1’ if v_{j+1} is a leaf, otherwise with $d(v_{j+1}) - 1$ ‘0’s followed by ‘1’. In $B(v_{j+1})$, we can save one bits for a code of v_{j+1} if v_{j+1} has two or more children. However, if $v_i = v_j$, then we require one bit to represent a inner subpath with “length zero”. So, such case needs one more bit than S_2 .

We denoted by S_3 obtained by adapting the above idea to S_2 .

Saving for Root Edges and Right Leaves

The last idea is as follows. Let r be the root vertex of T . If we omit $D(r)$ in S_1 (similarly S_2 and S_3), S_1 represents “ $d(r)$ trees”. Let S'_1 be a code obtained by omitting $D(r)$ in S_1 . By the decoding of S_1 , we can obtain $d(r)$ trees from S'_1 . Then we insert the root vertex with an edge to each tree. The resulting tree is T .

In addition, we can omit blocks for “right” leaves.

A vertex v is the *rightmost vertex* of T if v is the last vertex in preorder. Let v be the rightmost vertex of T , and assume that the parent of v is not r . All the siblings of v are leaves. A leaf ℓ is *right leaf* if ℓ is the rightmost vertex or ℓ is a sibling of the rightmost vertex. Since the number of right leaves can be compute

*1 If T is a star, S_2 satisfies $2n - 1$ bits too. However, in our coding, we focus on compressing a path structure.

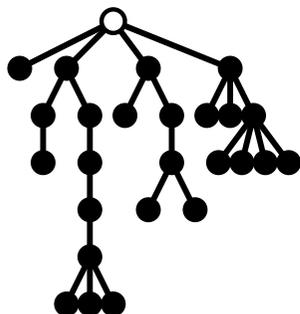


Fig. 2 A canonical tree for examples.

from the block for the parent of v , we can omit blocks for the right leaves. Note that if v is a child of r , we cannot omit.

Also we can save the last ‘1’, which is the last ‘1’ in the block for the parent of v , in the code, since the last bit is always ‘1’. This idea can be adopted even if the parent of v is the root.

We denote by S_4 and S_5 obtained by omitting root edges, right leaves and the last ‘1’ in S_2 and S_3 , respectively.

Examples

For example, S_1 , S_2 , S_3 , S_4 and S_5 for the canonical tree in Fig. 2 are:

$$S_1 = 000011001011101010100011111001101001111000111000011111,$$

$$S_2 = 00001100101111010100011111101001110111000011111,$$

$$S_3 = 000011001011111001011111101101110111000011111,$$

$$S_4 = 100101110101000111111010011101110000,$$

$$S_5 = 1001011110010111111011011101110000.$$

We have the following theorem.

Theorem 5.1 We can encode a canonical tree with S_1 , S_2 , S_3 , S_4 , S_5 in $O(n)$ time, and a decoding for each code can be done in $O(n)$ time using a stack.

6. Experimental Results

In this section, we show experimental results of the five codes S_1 , S_2 , S_3 , S_4 and S_5 explained in the previous section.

An environment for our experiment is as follows. (1) OS: FreeBSD 8.2-RELEASE, (2) CPU: AMD Phenom(tm) II X6 1065T Processor (2909.62-MHz K8-class CPU), (3) Main memory: 4GB and (4) Programming language: C.

Table 1 shows the average length of each code per a rooted tree with n vertices. Each column means S_1 (DFUDS), S_2 (DFUDS + difference), S_3 (DFUDS + difference + path compression), S_4 (DFUDS + difference + saving root edges and right leaves) and S_5 (DFUDS + difference + path compression + saving root edges and right leaves), respectively. ‘Optimal’ means the optimal average length of a code. Let \mathcal{T}_n be a set of rooted trees with n vertices. The optimal average length per tree can be obtained by calculating $\log |\mathcal{T}_n|$. For instance, for $n = 24$, S_4 needs $1.556n$ bits per a rooted tree with 24 vertices on the average. This also means S_4 needs 1.556 bits per a vertex in a rooted tree with 24 vertices. Since there is only one tree with n vertices for $n = 1$ or $n = 2$, we did not deal with the two cases here.

In this experiment, first, we enumerate all canonical trees with n vertices, then encode all the trees by each coding method, and then we calculate the average length of each code per tree.

All factors in Table 1 are plotted in Fig. 3 for each code. Fig. 3 shows that S_4 is the most compact among our codes. Comparing S_4 with the optimal length of code, S_4 is near to the optimal length. S_4 needs $1.556n$ bits per a rooted tree with $n = 24$ vertices on the average, and the optimal average length of code is $1.228n$ bits for the same tree. So, we conclude that S_4 is a compact code from this experimental results.

Unfortunately, path compression did not improve the average length. The two codes S_3 , S_5 which perform path compressions are slightly larger than S_2 and S_4 , respectively.

7. Conclusion

We have designed four new codes for a rooted tree. By coding canonical trees, we designed codes for (unordered) rooted trees. Our codes are based on DFUDS [1] which is a codes for an ordered tree. By improving DFUDS, we propose compact code for a rooted tree. Then, we have shown that our codes are compact by experiments.

# of vertices	$ S_1 $ (bits/tree)	$ S_2 $ (bits/tree)	$ S_3 $ (bits/tree)	$ S_4 $ (bits/tree)	$ S_5 $ (bits/tree)	Optimal (bits/tree)
$n = 1$	-	-	-	-	-	-
$n = 2$	-	-	-	-	-	-
$n = 3$	$1.667n$	$1.667n$	$1.667n$	$0.333n$	$0.500n$	$0.333n$
$n = 4$	$1.750n$	$1.750n$	$1.750n$	$0.562n$	$0.625n$	$0.500n$
$n = 5$	$1.800n$	$1.778n$	$1.800n$	$0.733n$	$0.800n$	$0.634n$
$n = 6$	$1.833n$	$1.800n$	$1.817n$	$0.883n$	$0.933n$	$0.720n$
$n = 7$	$1.857n$	$1.804n$	$1.821n$	$0.994n$	$1.039n$	$0.798n$
$n = 8$	$1.875n$	$1.810n$	$1.826n$	$1.090n$	$1.128n$	$0.856n$
$n = 9$	$1.889n$	$1.811n$	$1.827n$	$1.164n$	$1.199n$	$0.907n$
$n = 10$	$1.900n$	$1.812n$	$1.827n$	$1.226n$	$1.258n$	$0.949n$
$n = 11$	$1.909n$	$1.812n$	$1.827n$	$1.277n$	$1.306n$	$0.986n$
$n = 12$	$1.917n$	$1.812n$	$1.827n$	$1.320n$	$1.347n$	$1.018n$
$n = 13$	$1.923n$	$1.812n$	$1.826n$	$1.356n$	$1.382n$	$1.047n$
$n = 14$	$1.929n$	$1.811n$	$1.826n$	$1.387n$	$1.412n$	$1.072n$
$n = 15$	$1.933n$	$1.811n$	$1.825n$	$1.414n$	$1.437n$	$1.095n$
$n = 16$	$1.938n$	$1.810n$	$1.824n$	$1.437n$	$1.460n$	$1.115n$
$n = 17$	$1.941n$	$1.810n$	$1.824n$	$1.458n$	$1.480n$	$1.134n$
$n = 18$	$1.944n$	$1.809n$	$1.823n$	$1.477n$	$1.498n$	$1.151n$
$n = 19$	$1.947n$	$1.809n$	$1.823n$	$1.493n$	$1.514n$	$1.166n$
$n = 20$	$1.950n$	$1.809n$	$1.822n$	$1.508n$	$1.529n$	$1.181n$
$n = 21$	$1.952n$	$1.808n$	$1.822n$	$1.522n$	$1.542n$	$1.194n$
$n = 22$	$1.955n$	$1.808n$	$1.821n$	$1.534n$	$1.554n$	$1.206n$
$n = 23$	$1.957n$	$1.807n$	$1.821n$	$1.545n$	$1.564n$	$1.217n$
$n = 24$	$1.958n$	$1.807n$	$1.820n$	$1.556n$	$1.574n$	$1.228n$

Table 1 The average lengths of our codes. S_1 : DFUDS, S_2 : DFUDS + difference, S_3 : DFUDS + difference + path compression, S_4 : DFUDS + difference + saving root edges and right leaves, S_5 : DFUDS + difference + path compression + saving root edges and right leaves.

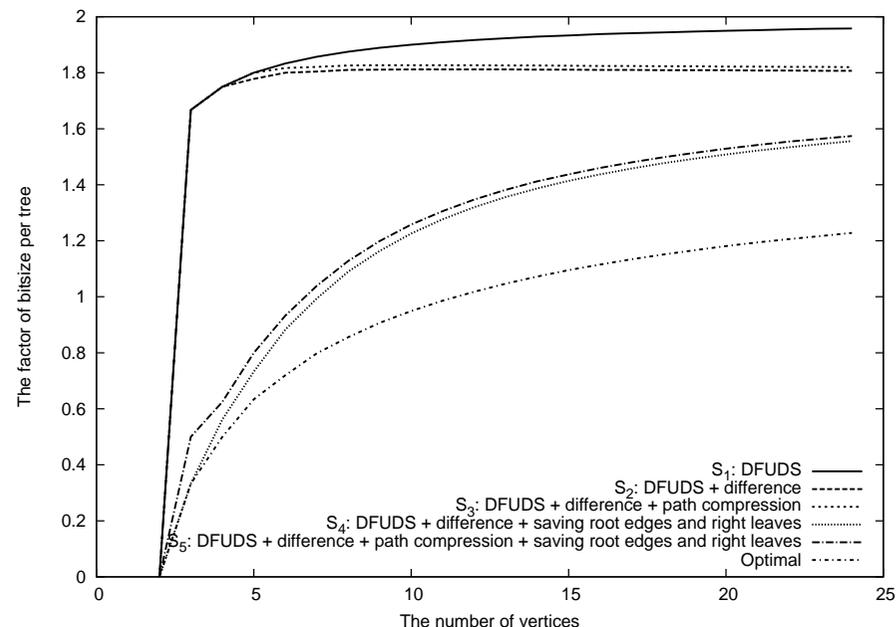


Fig. 3 The average lengths of each code.

The experimental results show that S_4 is compact, but the optimal average length seems to be properly smaller than the average length of S_4 . So, we want to know asymptotic behaviors of the two length. The optimal average length converges $1.564n$ bits asymptotically. Now, how many bits are required for S_4 asymptotically?

Other future tasks are to (1) design a more compact code for a rooted tree, and (2) design compact codes for other graph classes so that it attains (or is near to) the information-theoretically optimal bounds without an auxiliary table.

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