

Tree of Eigen-value of Two Dimensional Figure and its Application

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1. Introduction

Previously, the authors have tried to solve the eigen-value problem expressed by Helmholtz's differential equation using the outer normals of Green function [1], [7], where Helmholtz's differential equation is $\Delta\Phi + \lambda\Phi = 0$ in simply connected domain R , $\Phi = 0$ on an arbitrary boundary Γ and λ is eigen-value.

In this paper, we have used the finite difference approximation method, Jacobi method and error correction method [2], and have chosen several series of figures (shape of boundary is called as figure), and further have calculated their eigenvalues by digital computer, finally have made the tree of eigen-value [3]. As the result, it is possible to estimate optimum relaxation factor [4].

2. Method for calculating eigen-value

2.1 Lattice space and difference operator

We put a figure Γ on a regular square net whose cell length is h . Let Γ_h be the approximate boundary which is composed of the nearest links by Γ .

Generally the eigen-value of figure depends on the area of figure, so we have normalized the area M . By taking h^2 as the unit, the area surrounded by Γ_h is represented as follows;

$$M = Sh^2 = 1, \quad (1)$$

where S nearly equals to the number of lattice points surrounded by Γ_h .

We represent Helmholtz's difference equation as follows;

$$\left[-\frac{1}{h^2} \mathbf{A} + \lambda \mathbf{E} \right] \Phi = 0, \quad (2)$$

where \mathbf{A} is a matrix of difference operator, Φ is a vector of function Φ and \mathbf{E} is a unit matrix. Since $\Phi \neq 0$, we have,

$$\left| -\frac{1}{h^2} \mathbf{A} + \lambda \mathbf{E} \right| = 0, \quad (3)$$

Therefore, Helmholtz's equation results in eigen-value problem of matrix \mathbf{A} , and inverse matrix of \mathbf{A} is identical with Green function. Let λ be eigen-value of \mathbf{A} , and λ can be calculated from following equation,

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$$\lambda = \frac{1}{h^2} A = SA. \tag{4}$$

2.2 Correction of eigen-value

Let λ_i be i th analytical eigen-value, $\lambda_{i(h)}$ be i th experimental eigen-value and e_i be relative error, where

$$e_i = \frac{\lambda_i - \lambda_{i(h)}}{\lambda_i}. \tag{5}$$

From experiments we have gotten a relation $e_i \doteq a\lambda_{i(h)}$, where $a \doteq 0.08/S$, so we have following formula for correction

$$\bar{\lambda}_{i(h)} = \frac{\lambda_{i(h)}}{1 - 0.08 \lambda_{i(h)} / S}, \tag{6}$$

where $\bar{\lambda}_{i(h)}$ is corrected eigen-value.

When the boundary Γ is similar to Γ_h , that is, S is sufficiently large, the formula for correction (6) produces good results. In Fig. 1, one example of relative error e_i and \bar{e}_i is shown, where $\bar{e}_i = (\lambda_i - \bar{\lambda}_{i(h)}) / \lambda_i$.

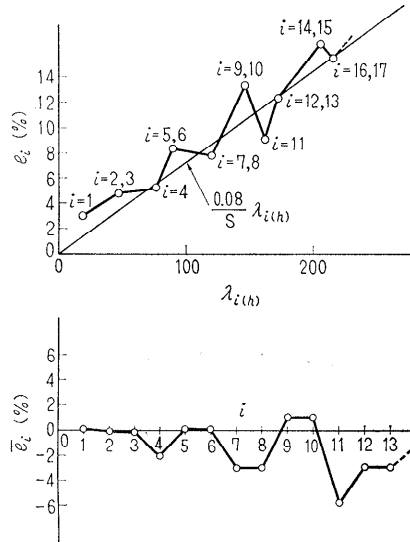


Fig. 1. An example of relative error e_i and \bar{e}_i (Figure: Square, Number of inner point: 81)

2.3 Explanation of formula for correction

Equation (6) can be represented in infinite progression as follows;

$$\bar{\lambda}_{i(h)} = \sum_{n=1}^{\infty} \left(\frac{0.08}{S} \right)^{n-1} \lambda^n_{i(h)}. \tag{7}$$

On the other hand, Helmholtz's equation can be represented in second and fourth derivatives as follows;

$$\begin{aligned} \left(\frac{\partial^4}{\partial x^4} + \frac{\partial^4}{\partial y^4} \right) \Phi(x, y) &= \left\{ \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right)^2 - 2 \frac{\partial^4}{\partial x^2 \partial y^2} \right\} \Phi(x, y) \\ &= \lambda^2 \Phi(x, y) - 2 \frac{\partial^4}{\partial x^2 \partial y^2} \Phi(x, y). \end{aligned}$$

$$\begin{aligned} \Delta\Phi(x, y) &= \frac{1}{h^2} \left\{ \Sigma^* \Phi(x', y') - 4\Phi(x, y) - 2 \sum_{n=2}^{\infty} \frac{h^{2n}}{(2n)!} \left(\frac{\partial^{2n}}{\partial x^{2n}} + \frac{\partial^{2n}}{\partial y^{2n}} \right) \Phi(x, y) \right\} \\ &= \frac{1}{h^2} \left\{ \Sigma^* \Phi(x', y') - 4\Phi(x, y) - 2 \sum_{n=2}^{\infty} \frac{(-1)^n h^{2n}}{(2n)!} \lambda^n \Phi(x, y) \right. \\ &\quad \left. + 2 \frac{h^4}{4!} \frac{\partial^4}{\partial x^2 \partial y^2} \Phi(x, y) + \dots \right\}, \end{aligned}$$

where $x' = x \pm h$, $y' = y \pm h$ and Σ^* indicates summation of four neighbour point of (x, y) .

Let $R(x, y)$ be higher order terms than fourth order terms in right hand side of above equation, we have

$$\begin{aligned} &\Sigma^* \Phi(x', y') - 4\Phi(x, y) + R(x, y) \\ &= -h^2 \lambda \Phi(x, y) + 2 \sum_{n=2}^{\infty} \frac{(-1)^n h^{2n}}{(2n)!} \lambda^n \Phi(x, y) \\ &= 2 \{ 1 - \cos(h\sqrt{\lambda}) \} \Phi(x, y) \quad (\lambda > 0). \end{aligned}$$

Since $R(x, y) = O(h^2)$, we neglect the term of $R(x, y)$. Let $\lambda_{(h)}$ be eigen-value of Helmholtz's difference equation, we have

$$\Sigma^* \Phi(x', y') - 4\Phi(x, y) = 2 \{ 1 - \cos(h\sqrt{\lambda}) \} \Phi(x, y) = h^2 \lambda_{(h)} \Phi(x, y). \tag{8}$$

Let $\bar{\lambda}_{(h)}$ be corrected value of $\lambda_{(h)}$, we have a following formula for correction.

$$\begin{aligned} \bar{\lambda}_{(h)} &= \left\{ \frac{1}{h} \cos^{-1} \left(1 - \frac{h^2 \lambda_{(h)}}{2} \right) \right\}^2 = S \left\{ \cos^{-1} \left(1 - \frac{\lambda_{(h)}}{2S} \right) \right\}^2 \\ &= S \sum_{n=1}^{\infty} \frac{(n-1)!}{(2n-1)!!} \cdot \frac{1}{2n} \left(\frac{\lambda_{(h)}}{2S} \right)^n, \end{aligned} \tag{9}$$

where $\lambda_{(h)}/2S \leq 2$, $(2n-1)!! = (2n-1)(2n-3)\dots 1$.

The progression in equation (7) has a similar tendency to equation (9), so the meanings of correction by equation (6) becomes clear. Particularly, in one dimensional region, equation (6) is a formula for complete correction.

Further, the correction by equation (6) is appropriate for case of convex figure. Because W. R. Wasow has shown that $\lim_{h \rightarrow 0} \lambda_{(h)} = \lambda (\lambda > \lambda_{(h)})$ when figure is convex and that there are some cases of $\lambda < \lambda_{(h)}$ when figure is concave [8].

3. Series of figure and examples of tree of eigen-value

For a systematic calculation of eigen-value, we have chosen several series of convex figures.

- (1) Series 1 Equilateral polygons
- (2) Series 2 Rectangles
- (3) Series 3 Rhombuses
- (4) Series 4 Trapeziums
- (5) Series 5 Isosceles trapezoids
- (6) Series 6 Right-angled triangles
- (7) Series 7 Isosceles triangles
- (8) Series 8 Ellipsoids

(9) Series 9 Lacked circles

(10) Series 10 Fan shapes

In Fig. 2, one exaple of correlation between eigen-values and geometric in-
formations is shown and the correlation of this sort has ever been considered
by G. Polya [5].

Further there are several common parameters to all figures, for examples, a
length of periphery [5], ratio of radius of maximum inscribed circle to one of
minimum circumscribed circle [3], etc. The correlation between eigen-value and
length of periphery L is shown in Fig. 3. We call these correlation graphs as
tree of eigen-valuc of figure.

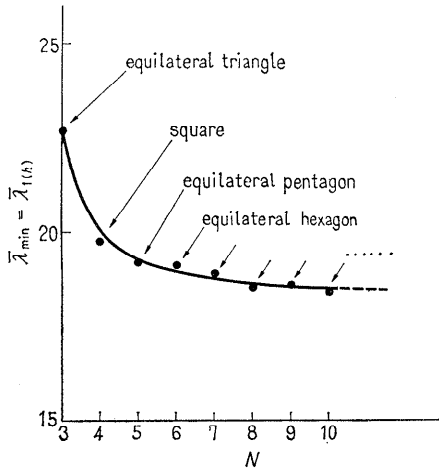


Fig. 2. Minimum eigenvalue of equilaterl polygons (series 1)

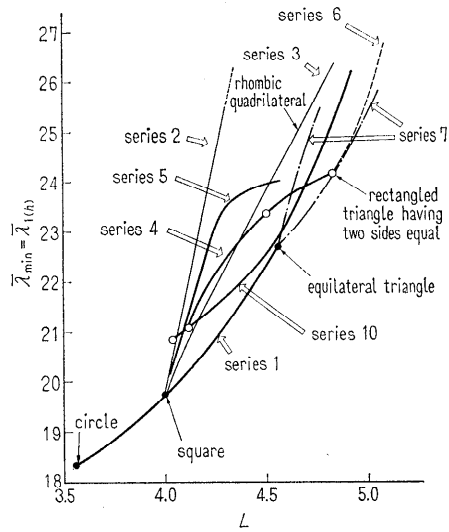


Fig. 3. Minimum eigen-value of various figures (Tree of eigen-value)

4. Application to estimation of optimum relaxation factor

4.1 Definition of optimum relaxation factor

We have dealt with the boundary value problem by successive over-relaxation
method [4]. Let R be a simply connected domain with a boundary Γ , I be the
interior of R and $u(x, y)$ be unknown function, then boundary value problem
is represented as follows;

$$\begin{aligned} \Delta u(x, y) &= -f(x, y) && \text{in } I \\ u(x, y) &= g(x, y) && \text{on } \Gamma, \end{aligned} \tag{10}$$

where $f(x, y)$ and $g(x, y)$ are given.

We have descretized a space and used a difference operator in place of a
differential operator. Let (i, j) be a lattice point (x, y) , then equation (10) can
be represented in matrix form as follows;

$$AU = K,$$

and in componentwise,

$$\sum_{j=1}^n a_{ij}u_j = k_i, \quad 1 \leq i \leq n, \quad (n \text{ is number of inner points}).$$

Let ω be relaxation factor of successive over-relaxation method and $u_i^{(m)}$ be m th value in successive process, then above equation is represented as follows;

$$a_{ij}u_i^{(m+1)} = a_{ij}u_i^{(m)} + \omega \left\{ - \sum_{j=1}^{i-1} a_{ij}u_j^{(m+1)} - \sum_{j=i+1}^n a_{ij}u_j^{(m)} + k_i - a_{ii}u_i^{(m)} \right\}. \quad (11)$$

Optimum value ω_{opt} of ω in equation (11) is given as follows [4];

$$\omega_{opt} = \frac{2}{1 + \sqrt{1 - \mu_{max}^2}}, \quad (12)$$

$$\mu_{max} = 1 - \lambda_{min}/4, \quad (13)$$

where λ_{min} is the minimum eigen-value of the matrix A .

4.2 Example of estimation

If μ_{max} is known, ω_{opt} can be calculated from equation (12). Fortunately, μ_{max} can be calculated from equation (13), and further λ_{min} can be calculated from equation (4).

For trial, we have calculated an ω_{opt} for case of rectangular, whose ratio of adjoining sides is 80:60. As Γ_h is broken at the four corners comparing with Γ (rectangular) for this case, S is calculated as $80 \times 60 - 2 = 4798$ and L is calculated as $7\sqrt{3}/3 \doteq 4.04$. The series 2 of Fig. 3 may be utilized and λ_{min} may be estimated as 20.3.

$$\tilde{\lambda}_{min} = \frac{\lambda_{min}}{S} = \frac{20.3}{4798} \doteq 0.0042,$$

$$\tilde{\mu}_{max} = 1 - \tilde{\lambda}_{min}/4 \doteq 0.9989,$$

$$\tilde{\omega}_{opt} = \frac{2}{1 + \sqrt{1 - \mu_{max}^2}} \doteq \frac{2}{1.05} \doteq 1.90.$$

For this case, ω_{opt} has been calculated as 1.9124 by J. S. Pearson and J. A. Harrison [6].

5. Conclusion

In this paper the authors have suggested the trees of eigen-value of various figures and developed the estimation method of optimum relaxation factor. It must be taken into consideration that this method can be used for calculating ω_{opt} only for case of arbitrary convex figures.

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