

最小 3-カット, 4-カット を計算するアルゴリズム

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あらまし $k = 3, 4$ に対し, 重み付きグラフの最小 k -カットを求める $O(n^{k-2}(nF(n, m) + C_2(n, m) + n^2)) = O(mn^k \log(n^2/m))$ 時間アルゴリズムを与える. ここで, n, m はグラフの点数, 辺数であり, $F(n, m)$ と $C_2(n, m)$ はそれぞれ n 点, m 辺グラフ上での最大流, 最小 2-カットを求める時間である. このアルゴリズムを拡張させて, 対称な劣モジュラシステムにおける最小 3-カットを効率良く計算することもできる.

A Fast Algorithm for Computing Minimum 3-Way and 4-Way Cuts

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Abstract For an edge-weighted graph G with n vertices and m edges, we present a new deterministic algorithm for computing a minimum k -way cut for $k = 3, 4$. The algorithm runs in $O(n^{k-2}(nF(n, m) + C_2(n, m) + n^2)) = O(mn^k \log(n^2/m))$ time for $k = 3, 4$, where $F(n, m)$ and $C_2(n, m)$ denote respectively the time bounds required to solve the maximum flow problem and the minimum 2-way cut problem in G . The bound for $k = 3$ matches the current best deterministic bound $\tilde{O}(mn^3)$ for weighted graphs, but improves the bound $\tilde{O}(mn^3)$ to $O(n(nF(n, m) + C_2(n, m) + n^2)) = O(\min\{mn^{8/3}, m^{3/2}n^2\})$ for unweighted graphs. The bound $\tilde{O}(mn^4)$ for $k = 4$ improves upon both the previous best deterministic bound $\tilde{O}(mn^5)$ and randomized bound $\tilde{O}(n^6)$ (for $m = o(n^2)$). The algorithm is then generalized to the problem of finding a minimum 3-way cut in a symmetric submodular system.

1 Introduction

Let G stand for an undirected graph with its edges being weighted by non-negative real numbers, and let n and m denote the numbers of vertices and edges, respectively. For an integer $k \geq 2$, a k -way cut is a partition $\{V_1, V_2, \dots, V_k\}$ of V consisting of k non-empty subsets. The problem of partitioning V into k non-empty subsets so as to minimize the weight sum of the edges between different subsets is called the *minimum k -way cut problem*. The problem has several important applications such as VLSI design [14], task allocation in distributed computing systems and network reliability. The 2-way cut problem (i.e., the problem of computing the edge-connectivity) can be solved in $\tilde{O}(nm)$ time [6, 15]. For $k = 3$, Hochbaum and Shmoys [7] proved that the problem in an unweighted planar graph can be solved in $O(n^2)$ time. However, the complexity status of the problem for general $k \geq 3$ in an arbitrary graph G has been open for several years. Goldschmidt and Hochbaum proved that the problem is NP-hard if k is an input parameter [5]. In the same article [5], they presented an $O(n^{k^2/2-3k/2+4}F(n, m))$ time algorithm for solving the minimum k -way cut problem, where $F(n, m)$ denotes the time required to find a minimum (s, t) -cut (i.e., a minimum 2-way cut that separates two specified vertices s and t) in an edge-weighted graph with n vertices and m edges, which can be obtained by applying a maximum flow algorithm. This running time is polynomial for any fixed k . Afterwards, Karger and Stein [11] proposed a randomized algorithm that solves the minimum k -way cut problem with high probability in $O(n^{2(k-1)}(\log n)^3)$ time.

For $k = 3$, Kapoor [10] and Kamidoi *et al.* [8] showed that the problem can be solved in $O(n^3F(n, m))$ time, which was then improved to $\tilde{O}(mn^3)$ by Burlet and Goldschmidt [1] and

Kamidoi *et al.* [9]. For $k = 4$, Kamidoi *et al.* [8] gave an $O(n^4 F(n, m)) = \tilde{O}(mn^5)$ time algorithm, and they recently proposed an $O(n^{2(k-2)}(F(n, m) + C_2(n, m)))$ time algorithm for the minimum k -way cut problem [9], where $C_2(n, m)$ denotes the time required to find a minimum 2-way cut in an edge-weighted graph with n vertices and m edges.

Let us call a non-empty and proper subset X of V a *cut*. Clearly, if we can identify the first cut V_1 in a minimum k -way cut $\{V_1, \dots, V_k\}$, then the rest of cuts V_2, \dots, V_k can be obtained by solving the minimum $(k-1)$ -way cut problem in the graph induced by $V - V_1$. The articles [1, 9] succeeded to characterize a set of $O(n^2)$ number of cuts which contains at least one such cut V_1 . Thus, by solving $O(n^2)$ minimum $(k-1)$ -way cut problems, a minimum k -way cut can be computed. For example, Burlet and Goldschmidt [1] showed that, given a minimum 2-way cut $\{X, V - X\}$ in G , such V_1 is a cut whose weight is less than $4/3$ of the weight of a minimum 2-way cut in G or in the induced subgraphs $G[X]$ and $G[V - X]$. Since it is known [17] that there are $O(n^2)$ cuts with weight less than $4/3$ of the weight of a minimum 2-way cut, and all those cuts can be enumerated in $\tilde{O}(mn^3)$ time, their approach yields an $\tilde{O}(mn^3)$ time minimum 3-way cut algorithm.

In this paper, we consider the minimum k -way cut problem for $k = 3, 4$, and give a new characterization of a set of $O(n)$ number of such candidate cuts for the first cut V_1 , on the basis of the submodularity of cut functions. We also show that those $O(n)$ cuts can be obtained in $O(n^2 F(n, m))$ time by using Vazirani and Yannakakis's algorithm for enumerating small cuts [19]. Therefore, we can find a minimum 3-way cut in $O(n^2 F(n, m) + nC_2(n, m)) = O(mn^3 \log(n^2/m))$ time and a minimum 4-way cut in $O(n^3 F(n, m) + n^2 C_2(n, m)) = O(mn^4 \log(n^2/m))$ time. The bound for $k = 3$ matches the current best deterministic bound $\tilde{O}(mn^3)$ for weighted graphs, but improves the bound $\tilde{O}(mn^3)$ to $O(\min\{mn^{8/3}, m^{3/2}n^2\})$ for unweighted graphs (since $F(n, m) = O(\min\{mn^{2/3}, m^{3/2}\})$ is known for unweighted graphs [2]). The bound $\tilde{O}(mn^4)$ for $k = 4$ improves upon both the previous best deterministic bound $\tilde{O}(mn^5)$ and randomized bound $\tilde{O}(n^6)$ (for $m = o(n^2)$). In the case of an edge-weighted planar graph G , we also shows that the algorithm can be implemented to run in $O(n^3)$ time for $k = 3$ and in $O(n^4)$ time for $k = 4$, respectively. The algorithm is then generalized to the problem of finding a minimum 3-way cut in a symmetric submodular system.

2 Preliminaries

2.1 Notations and definitions

A singleton set $\{x\}$ may be simply written as x , and “ \subset ” implies proper inclusion while “ \subseteq ” means “ \subset ” or “ $=$ ”. For a finite set V , a *cut* is defined as a non-empty and proper subset X of V . For two disjoint subsets $S, T \subset V$, we say that a cut X *separates* S and T if $S \subseteq X \subseteq V - T$ or $T \subseteq X \subseteq V - S$ holds. A subset $X \subseteq V$ *intersects* another subset $Y \subseteq V$ if $X - Y \neq \emptyset$, $Y - X \neq \emptyset$ and $X \cap Y \neq \emptyset$ hold, and X *crosses* Y if, in addition, $V - (X \cup Y) \neq \emptyset$ holds. A family \mathcal{X} of subsets of V is called *non-intersecting* (resp., *non-crossing*) if no two subsets $X, Y \in \mathcal{X}$ intersect (resp., cross) each other. It is possible that a non-crossing family \mathcal{X} contains a pair of intersecting subsets.

The following observation plays a key role in analyzing the time bound of our algorithm. We easily observe that $O(n)$ cuts belongs to a non-crossing set of cuts.

Lemma 1 *Let V be a non-empty finite set, and \mathcal{X} be a family of cuts in V such that, for each subset $X \in \mathcal{X}$, its complement $V - X$ does not belong to \mathcal{X} . Then $|\mathcal{X}| \leq 2|V| - 3$. \square*

A *set function* f on a ground set V is a function $f : 2^V \mapsto \mathbb{R}$, where \mathbb{R} is the set of real numbers. A set function f is called *submodular* if

$$f(X) + f(Y) \geq f(X \cap Y) + f(X \cup Y) \quad (1)$$

holds for every pair of subsets $X, Y \subseteq V$. An f is called *symmetric* if

$$f(X) = f(V - X) \text{ for all subsets } X \subseteq V. \quad (2)$$

For a symmetric and submodular set function f , it holds

$$f(X) + f(Y) \geq f(X - Y) + f(Y - X) \quad (3)$$

for every pair of subsets $X, Y \subseteq V$. A pair (V, f) of a finite set V and a set function f on V is called a *system*. It is called a *symmetric submodular system* if f is symmetric and submodular.

Given a system (V, f) , we define the minimum k -way cut problem as follows. A k -way cut is a partition $\pi = \{V_1, V_2, \dots, V_k\}$ of V consisting of k non-empty subsets. The weight $\omega_f(\pi)$ of a k -way cut π is defined by

$$\omega_f(\pi) = \frac{1}{2}(f(V_1) + f(V_2) + \dots + f(V_k)). \quad (4)$$

A k -way cut is called *minimum* if it has the minimum weight among all k -way cuts in (V, f) .

Let $G = (V, E)$ be an undirected graph with a set V of vertices and a set E of edges weighted by non-negative reals. For a non-empty subset $X \subseteq V$, let $G[X]$ denote the graph induced from G by X . For a subset $X \subseteq V$, its *cut value*, denoted by $c(X)$, is defined to be the sum of weights of edges between X and $V - X$, where $c(\emptyset)$ and $c(V)$ are defined to be 0. This set function c on V is called the *cut function* of G . The cut function c is symmetric and submodular, as easily verified. For a k -way cut $\pi = \{V_1, V_2, \dots, V_k\}$ of V , its weight in G is defined by $\omega_c(\pi) = \frac{1}{2}(c(V_1) + c(V_2) + \dots + c(V_k))$, which means the weight sum of the edges between different cuts in π .

2.2 Enumerating all 2-way cuts

In [19], Vazirani and Yannakakis presented an algorithm that finds all the 2-way cuts in G in the order of non-decreasing weights. The algorithm finds the next 2-way cut by solving at most $2n - 3$ maximum flow problems. We describe this result in a slightly more general way in terms of set functions. This algorithm will be used in Section 3 to obtain minimum 3-way and 4-way cuts.

Theorem 1 [19] *For a system (V, f) with $n = |V|$, 2-way cuts in (V, f) can be enumerated in the order of non-decreasing weights with $O(nF_f)$ time delay between two consecutive outputs, where F_f is the time required to find a minimum 2-way cut that separates specified two disjoint subsets $S, T \subset V$ in (V, f) . \square*

It is known that a non-empty and proper subset X that minimizes $g(X)$ in a submodular system (V, g) can be found in polynomial time by using the ellipsoid method [4]. In particular, the problem of finding a minimum 2-way cut which separates specified two disjoint subsets $S, T \subset V$ in (V, f) can be solved in polynomial time, since the problem is reduced to finding a minimum 2-way cut in the system (V', g) such that $V' = V - (S \cup T)$ and a submodular function $g : V' \rightarrow \mathbb{R}$ defined by $g(X) = f(X \cup S) - f(S)$.

For the cut function c in an edge-weighted graph G , it is well known that a minimum 2-way cut that separates specified two disjoint subsets $S, T \subset V$ can be found by solving a single maximum flow problem. Therefore $F_f = O(mn \log(n^2/m))$ holds if we use the maximum flow algorithm of [3], where n and m are the numbers of vertices and edges in G , respectively. In the planar graph case, we can enumerate cuts more efficiently by making use of dual graphs.

Call a simple path between s and t an s, t -path, and let $S(n, m)$ denote the time to compute a shortest s, t -path in an edge-weighted graph G with n vertices and m edges.

Lemma 2 *For an edge-weighted graph $G = (V, E)$ with $n = |V|$ and $m = |E|$, cycles in G can be enumerated in the order of non-decreasing lengths, with $O(S(n, m))$ time delay between two consecutive outputs, where the first cycle can be found in $O(mS(n, m))$ time. \square*

Corollary 1 *For an edge-weighted planar graph $G = (V, E)$ with $n = |V|$, 2-way cuts in G can be enumerated in the order of non-decreasing weights with $O(n)$ time delay between two consecutive outputs, where the first 2-way cut can be found in $O(n^2)$ time. \square*

3 Minimum 3-Way and 4-Way Cuts

Let $\pi = \{V_1, \dots, V_k\}$ be a minimum k -way cut in a system (V, f) . Suppose that the first cut V_1 in π is known. Then we need to compute a minimum k -way cut $\{V_1, \dots, V_k\}$ in (V, f) under the restriction that V_1 is fixed. In the case of a graph, the problem can be reduced to finding a minimum $(k-1)$ -way cut in the induced subgraph $G[V - V_1]$. For $k = 3, 4$, we now show that such a cut V_1 can be obtained from among $O(n)$ number of cuts.

Theorem 2 For a symmetric submodular system (V, f) with $n = |V| \geq 4$, let

$$\{X_1, V - X_1\}, \{X_2, V - X_2\}, \dots, \{X_r, V - X_r\}$$

be the first r smallest 2-way cuts in the order of non-decreasing weights, where r is the first integer r such that X_r crosses some X_q ($1 \leq q < r$). Let us denote $Y_1 = X_q - X_r$, $Y_2 = X_q \cap X_r$, $Y_3 = X_r - X_q$, and $Y_4 = V - (X_q \cup X_r)$. Then:

- (i) There is a minimum 3-way cut $\{V_1, V_2, V_3\}$ of (V, f) such that $V_1 = X_i$ or $V_1 = V - X_i$ for some $i \in \{1, 2, \dots, r-1\}$, or $\{V_1, V_2, V_3\} = \{Y_j, Y_{j+1}, V - (Y_j \cup Y_{j+1})\}$ for some $j \in \{1, 2, 3, 4\}$ (where $Y_{j+1} = Y_1$ for $j = 4$).
- (ii) There is a minimum 4-way cut $\{V_1, \dots, V_4\}$ of (V, f) such that $V_1 = X_i$ or $V_1 = V - X_i$ for some $i \in \{1, 2, \dots, r-1\}$, or $\{V_1, \dots, V_4\} = \{Y_1, Y_2, Y_3, Y_4\}$.

Proof. We have $f(X_1) \leq f(X_2) \leq \dots \leq f(X_r)$ by assumption.

(i) Let a minimum 3-way cut in G be denoted by $\{V_1, V_2, V_3\}$ with $f(V_1) \leq \min\{f(V_2), f(V_3)\}$. If $f(V_1) < f(X_r)$, this implies that $V_1 = X_i$ or $V_1 = V - X_i$ for some $i < r$. Therefore assume $f(V_1) \geq f(X_r)$. Thus, $\omega_f(\{V_1, V_2, V_3\}) \geq \frac{3}{2}f(X_r)$ holds. Now the cuts X_q and X_r cross each other, and $f(X_q) \leq f(X_r)$ holds by $q < r$. By (3), we have $f(X_q) + f(X_r) \geq f(X_q - X_r) + f(X_r - X_q)$. Hence at least one of $f(X_q - X_r)$ and $f(X_r - X_q)$ is equal to or less than $\max\{f(X_q), f(X_r)\}$ ($= f(X_r)$). Thus, $f(Y_i) \leq f(X_r)$ holds for $i = 1$ or $i = 3$. Assume that $f(X_h - X_j) \leq f(X_r)$ holds for $\{h, j\} = \{q, r\}$. Similarly, we obtain $\min\{f(X_q \cap X_r), f(X_q \cup X_r)\} \leq f(X_r)$ by (1). Thus, $f(Y_i) \leq f(X_r)$ holds for $i = 2$ or $i = 4$ (note that $f(X_q \cup X_r) = f(V - (X_q \cup X_r))$). Therefore, there is an index $j \in \{1, 2, 3, 4\}$ such that $f(Y_j) \leq f(X_r)$ and $f(Y_{j+1}) \leq f(X_r)$ (where Y_{j+1} implies Y_1 for $j = 4$). Clearly, $f(V - (Y_j \cup Y_{j+1}))$ is equal to $f(X_q)$ or $f(X_r)$. Therefore, for the 3-way cut $\{Y_j, Y_{j+1}, V - (Y_j \cup Y_{j+1})\}$, we have $\omega_f(\{Y_j, Y_{j+1}, V - (Y_j \cup Y_{j+1})\}) \leq \frac{3}{2}f(X_r) \leq \omega_f(\{V_1, V_2, V_3\})$. This implies that $\{Y_j, Y_{j+1}, V - (Y_j \cup Y_{j+1})\}$ is also a minimum 3-way cut.

(ii) Let a minimum 4-way cut in G be denoted by $\{V_1, V_2, V_3, V_4\}$ with $f(V_1) \leq \min\{f(V_2), f(V_3), f(V_4)\}$. Assume that $f(V_1) \geq f(X_r)$ holds, since otherwise (i.e., $f(V_1) < f(X_r)$), we are done. Thus, $2f(X_r) \leq 2f(V_1) \leq \omega_f(\{V_1, V_2, V_3, V_4\})$. From inequalities (1) - (3), we then obtain

$$2f(X_r) \geq f(X_q) + f(X_r) \geq \frac{1}{2}[f(X_q - X_r) + f(X_r - X_q) + f(X_q \cap X_r) + f(V - (X_q \cup X_r))].$$

Therefore, we have $\frac{1}{2}[f(X_q - X_r) + f(X_r - X_q) + f(X_q \cap X_r) + f(V - (X_q \cup X_r))] \leq f(X_q) + f(X_r) \leq 2f(X_r) \leq \omega_f(\{V_1, V_2, V_3, V_4\})$, indicating that $\{X_q - X_r, X_r - X_q, X_q \cap X_r, V - (X_q \cup X_r)\}$ is also a minimum 4-way cut in (V, f) . \square

Now we are ready to describe a new algorithm for computing minimum 3-way and 4-way cuts in an edge-weighted graph G . In the algorithm, minimum 2-way cuts will be stored in \mathcal{X} in the non-decreasing order, until \mathcal{X} becomes crossing, and an $O(n)$ number of k -way cuts will be stored in \mathcal{C} , from which a k -way cut of the minimum weight is chosen.

MULTIWAY

Input: An edge-weighted graph $G = (V, E)$ with $|V| \geq 4$ and an integer $k \in \{3, 4\}$.

Output: A minimum k -way cut π .

- 1 $\mathcal{X} := \mathcal{C} := \emptyset; i := 1;$
- 2 **while** \mathcal{X} is non-crossing **do**
- 3 Find the i -th minimum 2-way cut $\{X_i, V - X_i\}$ in G ;
- 4 $\mathcal{X} := \mathcal{X} \cup \{X_i\};$

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5   if  $|V - X_i| \geq k - 1$  then find a minimum  $(k - 1)$ -way cut  $\{Z_1, \dots, Z_{k-1}\}$  in  $G[V - X_i]$ ,
      and add the  $k$ -way cut  $\{X_i, Z_1, \dots, Z_{k-1}\}$  to  $\mathcal{C}$ ;
6   if  $|X_i| \geq k - 1$  then find a minimum  $(k - 1)$ -way cut  $\{Z'_1, \dots, Z'_{k-1}\}$  in  $G[X_i]$ ,
      and add the  $k$ -way cut  $\{Z'_1, \dots, Z'_{k-1}, V - X_i\}$  to  $\mathcal{C}$ ;
7    $i := i + 1$ 
8   end; /* while */
9   Let  $X_r$  be the last cut added to  $\mathcal{X}$ , and choose a cut  $X_q \in \mathcal{X}$  that crosses  $X_r$ ,
      where we denote  $Y_1 = X_q \setminus X_r$ ,  $Y_2 = X_q \cap X_r$ ,  $Y_3 = X_r - X_q$ , and  $Y_4 = V - (X_q \cup X_r)$ ;
10  if  $k = 3$  then add to  $\mathcal{C}$  3-way cuts  $\{Y_j, Y_{j+1}, V - (Y_j \cup Y_{j+1})\}$ ,  $j \in \{1, 2, 3, 4\}$ 
      (where  $Y_{j+1} = Y_1$  for  $j = 4$ );
11  if  $k = 4$  then add 4-way cut  $\{Y_1, Y_2, Y_3, Y_4\}$  to  $\mathcal{C}$ ;
12  Output a  $k$ -way cut  $\pi$  in  $\mathcal{C}$  with the minimum weight.

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The correctness of algorithm MULTIWAY follows from Theorem 2. To analyze the running time of MULTIWAY, let $C_k(n, m)$ ($k \geq 2$) denote the time required to find a minimum k -way cut in an edge-weighted graph with n vertices and m edges.

By Lemma 1, the number r of iterations of the while-loop is at most $3n - 5 = O(n)$. Therefore, lines 5 and 6 in MULTIWAY requires $O(nC_{k-1}(n, m))$ time in total. The total time required to check whether \mathcal{X} is crossing or not is $O(rn^2) = O(n^3)$. By Theorem 1, r minimum 2-way cuts can be enumerated in the non-decreasing order in $O(rnF(n, m)) = O(n^2F(n, m))$ time, where $F(n, m)$ denotes the time required to find a minimum (s, t) -cut (i.e., a minimum 2-way cut that separates two specified vertices s and t) in an edge-weighted graph with n vertices and m edges. Summing up these, we establish the following result.

Theorem 3 *For an edge-weighted graph $G = (V, E)$, where $n = |V| \geq 4$ and $m = |E|$, a minimum 3-way cut and a minimum 4-way cut can be computed in $O(n^2F(n, m) + nC_2(n, m) + n^3)$ and $O(n^2F(n, m) + nC_3(n, m) + n^3) = O(n^3F(n, m) + n^2C_2(n, m) + n^4)$ time, respectively. \square*

For a planar graph G , we can obtain better bounds by applying Corollary 1.

Corollary 2 *For an edge-weighted planar graph $G = (V, E)$, where $n = |V| \geq 4$ and $m = |E|$, a minimum 3-way cut and a minimum 4-way cut can be computed in $O(n^3)$ and $O(n^4)$ time, respectively. \square*

4 3-Way Cuts in Symmetric Submodular Systems

4.1 General case

Let (V, f) be a symmetric submodular system. Let us consider whether the algorithm MULTIWAY can be extended to find a minimum k -way cut in (V, f) for $k = 3, 4$. In the case of a graph $G = (V, E)$, if the first cut V_1 in a minimum k -way cut $\{V_1, \dots, V_k\}$ is known, then the remaining task of finding cuts V_2, \dots, V_k can be reduced to computing a minimum $(k - 1)$ -way cut in the induced subgraph $G[V - V_1]$. However, even if the first cut V_1 in a minimum k -way cut $\{V_1, \dots, V_k\}$ is known in (V, f) , finding the rest of cuts V_2, \dots, V_k may not be directly reduced to the minimum $(k - 1)$ -way cut problem in a certain symmetric submodular system $(V - V_1, f')$ (because, we do not have any concept corresponding to the induced subgraph $G[V - V_1]$ in a symmetric submodular system (V, f)). Thus, we need to find a procedure to compute a minimum k -way cut $\{V_1, \dots, V_k\}$ in (V, f) under the restriction that V_1 is fixed. In what follows, we show that such a procedure can be constructed for $k = 3$ (but the case of $k = 4$ is still open).

For this, we first define a set function f' on $V' = V - V_1$ from the cut V_1 .

Lemma 3 *For a symmetric submodular system (V, f) and a subset $V_1 \subset V$, the set function f' on $V' = V - V_1$, defined by $f'(X) = f(X) + f(V' - X) - f(V')$, $X \subseteq V'$, is symmetric and submodular.*

Proof. Clearly f' is symmetric by definition. For any $X, Y \subseteq V$, we obtain $f'(X) + f'(Y) = f(X) + f(V' - X) - f'(V) + f(Y) + f(V' - Y) - f'(V) \geq f(X \cap Y) + f(X \cup Y) + f(V' - (X \cap Y)) + f(V' - (X \cup Y)) - 2f'(V) = f'(X \cap Y) + f'(X \cup Y)$. \square

Note that for a 3-way cut $\pi = \{V_1, V_2, V_3\}$ in (V, f) , its weight $\omega_f(\pi)$ is given by $\frac{1}{2}(f(V_1) + f(V_2) + f(V - V_1 - V_2)) = f(V_1) + \frac{1}{2}(f(V_2) + f(V' - V_2) - f(V_1)) = f(V_1) + \frac{1}{2}f'(V_2)$ for $V' = V - V_1$. Therefore, a minimum 3-way cut $\{V_1, V_2, V_3\}$ in (V, f) for a specified V_1 can be obtained by solving the minimum 2-way cut problem in the system (V', f') .

For a symmetric submodular system (V, f) , it is known that a minimum 2-way cut in a symmetric submodular system can be computed combinatorially in $O(n^3 T_f)$ time [18, 16], where T_f is the time to evaluate the function value $f(X)$ for a given subset $X \subseteq V$.

Now we are ready to extend the algorithm MULTIWAY so as to find a minimum 3-way cut in (V, f) . By Theorem 1, we can enumerate 2-way cuts of (V, f) in the order of non-decreasing weights with $O(nF_f)$ time delay, where F_f is the time required to find a minimum 2-way cut that separates specified two disjoint subsets $S, T \subset V$ in (V, f) . Thus, we can enumerate the first r minimum 2-way cuts of (V, f) in $O(rnF_f) = O(n^2 F_f)$ time, using the result $r = O(n)$ of Lemma 1. Therefore, we can compute a minimum 3-way cut $\{V_1, V_2, V_3\}$ in (V, f) under the restriction that V_1 is fixed. Summarizing these up, we have the following result.

Theorem 4 *For a symmetric and submodular system (V, f) with $n = |V| \geq 3$, a minimum 3-way cut can be computed in $O(n^2 F_f + n^4 T_f)$ time, where F_f is the time required to find a minimum 2-way cut that separates specified two disjoint subsets $S, T \subset V$ in (V, f) , and T_f is the time to evaluate the function value $f(X)$ for a given subset $X \subseteq V$.* \square

4.2 Cut function of a hypergraph

Now we elaborate upon the result of Theorem 4, assuming that f is the cut function c of a hypergraph. Let $H = (V, E)$ be an edge-weighted hypergraph with a vertex set V and a hyper-edge set E , where a hyper-edge e is defined as a non-empty subset of V . For a hyper-edge $e \in E$, $V(e)$ denotes the set of end vertices of e (i.e., the vertices incident to e). A *cut function* c in H is defined by $c(X) = \{w(e) \mid V(e) \cap X \neq \emptyset, V(e) \cap (V - X) \neq \emptyset\}$, $X \subseteq V$, where $w(e)$ is the weight of edge e . It is easy to observe that the cut function c in a hypergraph H is also symmetric and submodular. We define the weight $\omega_c(\pi)$ of a k -way cut $\{V_1, \dots, V_k\}$ also by (4).

Remark: The weight $\omega_c(\pi)$ of a minimum 2-way cut π is equal to the minimum weight sum of edges whose removal makes the hypergraph disconnected. This is the same as the case of the cut function in a graph. For $k \geq 3$, however, $\omega_c(\pi)$ of a minimum k -way cut $\pi = \{V_1, \dots, V_k\}$ may not mean the minimum weight sum γ_H of edges whose removal generates at least k components, where

$$\gamma_H = \min\{\gamma_H(\pi) \mid k\text{-way cut } \pi\}, \quad (5)$$

$$\gamma_H(\pi) = \{w(e) \mid e \in E, V(e) \not\subseteq V_i \text{ for all } V_i \in \pi\}.$$

This is different from the case of a graph. The reason is because the weight $w(e)$ of a hyper-edge e may contribute to $\omega_c(\pi)$ by more than 1 if e is incident to more than two subsets in π . \square

Let $H = (V, E)$ be a hypergraph with $|E| \geq |V|$. Given two specified vertices $s, t \in V$, it is known [13] that a minimum 2-way cut separating s and t in H can be computed by solving a single maximum flow problem in the auxiliary digraph with $|V| + 2|E|$ vertices and $2d_H + 2|E|$ edges, where $d_H = \sum_{e \in E} |V(e)|$. Thus, a minimum 2-way cut separating two disjoint subsets $S, T \subset V$ can be computed in $F_c = F(|V| + 2|E|, 2d_H + 2|E|) = \tilde{O}(|E|d_H)$ time by computing a minimum 2-way cut separating s and t in the hypergraph obtained from H by contracting S and T into single vertices s and t , respectively.

For a given subset $X \subset V' = V - V_1$, the function value $f'(X) = c(X) + c(V' - X) - c(V_1)$ can be evaluated in $T_c = O(n + d_H)$ time. Hence, by Theorem 4, we can compute a minimum 3-way cut in $O(|V|^2 F_c + |V|^4 T_c) = \tilde{O}(|V|^2 |E| d_H + |V|^4 (|V| + d_H)) = \tilde{O}(|V|^4 + |V|^2 |E|) d_H$ time.

The running time can be slightly improved as follows. Notice that for a 3-way cut $\pi = \{V_1, V_2, V_3\}$ in $H = (V, E)$, its weight $\omega_c(\pi)$ is written as

$$\begin{aligned} \omega_c(\pi) &= \sum \{w(e) \mid e \in E, |\{i \mid V_i \cap V(e) \neq \emptyset\}| = 2\} \\ &\quad + \frac{3}{2} \sum \{w(e) \mid e \in E, |\{i \mid V_i \cap V(e) \neq \emptyset\}| = 3\}. \end{aligned}$$

For a given cut V_1 , let us define an edge-weighted hypergraph $H[V_1] = (V', E')$ induced from H by V_1 by $V' = V - V_1$ and $E' = \{e \in E \mid V(e) \cap (V - V_1) \neq \emptyset\}$, where for each hyper-edge $e \in E'$, the set $V'(e)$ of its end vertices and its weight $w'(e)$ are redefined by $V'(e) = V(e) - V_1$ and

$$w'(e) = \begin{cases} w(e) & \text{if } V'(e) = V(e) \\ w(e)/2 & \text{if } V'(e) \subset V(e). \end{cases}$$

Hence, for a 2-way cut $\pi' = \{V_2, V_3\}$ in $H[V_1] = (V', E')$, its weight $\omega_{c'}(\pi') = \sum \{w'(e) \mid e \in E', V'(e) \cap V_2 \neq \emptyset \neq V'(e) \cap V_3\}$ (where c' denotes the cut function in $H[V_1]$) is equal to $\sum \{w(e) \mid e \in E', V(e) \cap V_2 \neq \emptyset \neq V(e) \cap V_3, V(e) \cap V_1 = \emptyset\} + \sum \{w(e)/2 \mid e \in E', V'(e) \cap V_2 \neq \emptyset, V'(e) \cap V_3 \neq \emptyset, V'(e) \cap V_1 \neq \emptyset\}$. Thus, $c(V_1) + \omega_{c'}(\pi') = \omega_c(\pi)$ holds for a 3-way cut $\pi = \{V_1, V_2, V_3\}$ and the cut function c in H . Therefore, for a fixed cut V_1 , we can find a minimum 3-way cut $\{V_1, V_2, V_3\}$ in H by computing a minimum 2-way cut $\{V_2, V_3\}$ in $H[V_1]$. It is known that a minimum 2-way cut in a hypergraph $H = (V, E)$ can be obtained in $O(|V|d_H + |V|^2 \log |V|)$ time [12]. Since we need to solve $O(n)$ number of minimum 2-way cut problems in our algorithm, the time complexity becomes $O(|V|^2 F(|V| + |E|, d_H) + |V|^2 (d_H + |V| \log |V|)) = \tilde{O}(|V|^2 |E| d_H)$, assuming $|E| \geq |V|$.

Corollary 3 *For an edge-weighted hypergraph $H = (V, E)$, a 3-way cut π minimizing $\omega_c(\pi)$ can be computed in $\tilde{O}(n^2 m d_H)$ time, where $n = |V|$, $m = |E| \geq n$, $d_H = \sum_{e \in E} |V(e)|$ and c is the cut function in H . \square*

As remarked in the above, the weight of $\omega_c(\pi)$ of a minimum 3-way cut π in a hypergraph $H = (V, E)$ may not give the γ_H of (5). However, for any 3-way cut π , it holds $\omega_c(\pi) \leq \frac{3}{2} \gamma_H(\pi)$. Therefore, the minimum value $\omega_c(\pi)$ over all 3-way cuts π is at most 1.5 of γ_H .

Corollary 4 *For an edge-weighted hypergraph $H = (V, E)$, there is a 1.5-approximation algorithm for the problem of minimizing the sum of weights of hyper-edges whose removal leaves at least 3 components. The algorithm runs in $\tilde{O}(n^2 m d_H)$ time, where $n = |V|$, $m = |E|$ and $d_H = \sum_{e \in E} |V(e)| \geq n$. \square*

For $k = 4$, it is not known how to find a minimum 4-way cut $\{V_1, \dots, V_4\}$ in a symmetric submodular system (or in a hypergraph) under the condition that V_1 is fixed. By using the above argument, we can find a minimum 4-way cut in a hypergraph $H = (V, E)$ if every hyper-edge e has at most three incident vertices (i.e., $2 \leq |V(e)| \leq 3$ for all $e \in E$). This is because if $|V(e)| \leq 3$ for all $e \in E$, then it holds $\omega_c(\pi) = c(V_1) + \omega_{c'}(\pi')$ for the weight $\omega_c(\pi)$ of 4-way cut $\pi = \{V_1, V_2, V_3, V_4\}$ in H and the weight $\omega_{c'}(\pi')$ of a 3-way cut $\pi' = \{V_2, V_3, V_4\}$ in the induced hypergraph $H[V_1]$ as defined above. The algorithm runs in $\tilde{O}(|V|^2 F_c + |V|(|V|^2 |E| d_H)) = \tilde{O}(|V|^3 |E| d_H)$ time. Also, in this class of hypergraphs, a 4-way cut π that minimizes the weight $\omega_c(\pi)$ is a 1.5-approximation to the problem of finding a 4-way cut π that minimizes $\gamma_H(\pi)$.

Corollary 5 *Let $H = (V, E)$ be an edge-weighted hypergraph such that every hyper-edge $e \in E$ has at most three incident vertices, and let $n = |V|$, $m = |E| \geq n$ and $d_H = \sum_{e \in E} |V(e)|$. Then a 4-way cut π that minimizes $\omega_c(\pi)$ can be computed in $\tilde{O}(n^3 m d_H)$ time, and its $\gamma_H(\pi)$ value is at most 1.5 of the minimum weight sum γ_H of hyper-edges whose removal leaves at least 4 components in H . \square*

5 Concluding Remark

In this paper, we proposed an algorithm for computing minimum 3-way and 4-way cuts in a graph, based on the enumeration algorithm of 2-way cuts in the non-decreasing order. The algorithm is then extended to the problem of finding a minimum 3-way cut in a symmetric submodular system. As a result of this, the minimum 3-way cut problem in a hypergraph can be solved in polynomial time. It is left for future work how to extend the algorithm to the case of $k \geq 5$ in graphs and the case of $k \geq 4$ in symmetric submodular systems (or in hypergraphs). Very recently, we proved that the minimum k -way cuts in graphs can be computed in $O(mn^k \log(n^2/m))$ time for $k = 5, 6$.

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