

# The Divided Difference Table From A Matrix Viewpoint

YASUHIKO IKEBE\*, ISSEI FUJISHIRO\* and YASUSUKE ASAYAMA\*\*

Given a complex function  $w=f(z)$  defined in some region containing distinct points  $z_1, \dots, z_n$ , we consider the divided difference table in the form of the divided difference matrix  $f^+(z_1, \dots, z_n)$  whose  $(i, j)$  component equals  $f(z_i, \dots, z_j)$  for  $i \leq j$  and 0 elsewhere. Two theorems are proved: the first asserts that  $f \rightarrow f^+$  is an algebraic homomorphism; the second gives a Cauchy contour-integral representation of  $f^+(z_1, \dots, z_n)$ , which also equals the Cauchy formula for  $f(z^+)$ , where  $z^+$  denote the  $f^+$ -matrix corresponding to  $f(z)=z$  and where  $f(z)$  is assumed analytic in a region containing  $z_1, \dots, z_n$ .

## 1. Introduction

Divided differences are a classical but important tool in numerical analysis. Let  $w=f(z)$  be a function of a complex variable, analytic in some region  $D$  containing a set of distinct points  $z_1, \dots, z_n$ . Given the functional values  $f(z_1), \dots, f(z_n)$ , the standard method for computing the divided differences  $f(z_i, z_{i+1}, \dots, z_j)$ , where  $i < j$ , is through the use of recursive relation

$$f(z_i, z_{i+1}, \dots, z_j) = \frac{1}{z_i - z_j} \{ f(z_i, \dots, z_{j-1}) - f(z_{i+1}, \dots, z_j) \}$$

Consider the divided difference matrix, denoted by  $f^+(z_1, \dots, z_n)$ , whose  $(i, j)$  the entry equals  $f(z_i, \dots, z_j)$ , where  $i \leq j$ :

$$f^+(z_1, \dots, z_n) = \begin{bmatrix} f(z_1) & f(z_1, z_2) & \dots & f(z_1, \dots, z_n) \\ & f(z_2) & \dots & f(z_2, \dots, z_n) \\ & & \ddots & \\ & & & f(z_n) \\ 0 & & & \end{bmatrix}.$$

This is a slight rearrangement of the conventional divided difference table such as the one below:

$$\begin{array}{cccc} f(z_1) & & & \\ & f(z_1, z_2) & & \\ f(z_2) & & f(z_1, z_2, z_3) & \dots \\ & f(z_2, z_3) & & \\ & & \ddots & \\ & & & \ddots \end{array}$$

\*Institute of Information Sciences and Electronics, University of Tsukuba, Tsukuba City, Ibaraki 305, Japan.

\*\*Central Research Laboratory Engineering Center, Sharp Co., Ltd.

$f(z_n)$

In this paper, we will show that the divided difference matrix reveals a deeper mathematical structure existing among the divided differences. To be more specific, we will prove two theorems on  $f^+(z_1, \dots, z_n)$ ; THEOREM 1 gives a matrix representation of basic computational rules for divided differences and shows that the map  $f \rightarrow f^+$  is an algebraic homomorphism; THEOREM 2 gives a Cauchy integral representation of the divided difference matrix  $f^+(z_1, \dots, z_n)$ .

### Theorem 1. (Homomorphism Theorem)

In the below,  $f$  and  $g$  denote functions of a complex variable.

(a)  $(\alpha f + \beta g)^+ = \alpha f^+ + \beta g^+$ , where  $\alpha$  and  $\beta$  are constants;

(b)  $(fg)^+ = f^+ g^+ = g^+ f^+$

(c) When  $f(z) = 1$ ,  $f^+ = I = I$  (identity matrix);

(d) When  $f(z) = z$ ,  $f^+ = z^+ = \begin{bmatrix} z_1 & 1 & 0 \\ & \ddots & \vdots \\ & & \ddots & 1 \\ 0 & & & z_n \end{bmatrix}$ ;

(e)  $(1/g)^+ = (g^+)^{-1}$ , where  $g(z_1) \neq 0, \dots, g(z_n) \neq 0$ ;

(f)  $(f/g)^+ = f^+ (g^+)^{-1} = (g^+)^{-1} f^+$ ,

where  $g(z_1) \neq 0, \dots, g(z_n) \neq 0$ .

The proof of (a) through (f) is easy, where (b) is a matrix representation of Leibniz' formula [1, p. 5] (or, viewed differently, (b) is a good way to memorize Leibniz' formula).

**Corollary 1.** If  $f(z)$  is a rational function of  $z$ , where the denominator does not vanish at each point  $z_i$  ( $i=1, \dots, n$ ), or, a power series in  $z$  whose radius of

convergence exceeds each of  $|z_1|, \dots, |z_n|$ , then  $f^+(z_1, \dots, z_n) = f(z^+)$ .

The corollary generalizes to:

**Theorem 2.** (Integral Representation Theorem)

Let  $w=f(z)$  be analytic in a region  $D$  which contains the given set of distinct points  $z_1, \dots, z_n$  in its interior. Let  $C$  be a contour in  $D$ , enclosing  $z_1, \dots, z_n$  in its interior. Then

$$f^+(z_1, \dots, z_n) = \frac{1}{2\pi i} \int_C f(t)(tI - z^+)^{-1} dt = f(z^+),$$

where  $z^+$  is defined in Theorem 1 (d). This gives an integral representation of the divided difference matrix  $f^+(z_1, \dots, z_n)$ .

**Proof.** By direct computation, the  $(i, j)$ th entry of

$$(tI - z^+)^{-1} = \begin{bmatrix} t - z_1 & -1 & 0 \\ & \ddots & \vdots \\ 0 & & -1 \\ & & & t - z_n \end{bmatrix}^{-1}$$

equals  $(t - z_i)^{-1}(t - z_{i+1})^{-1} \dots (t - z_j)^{-1}$ , where  $i \leq j$ , and 0 elsewhere. Hence the proof reduces to that of

$$f(z_1, \dots, z_n) = \frac{1}{2\pi i} \int_C \frac{f(t)}{(t - z_1) \dots (t - z_n)} dt.$$

This is a known identity [3, p. 247, or 4, p. 171] whose proof is included here for self-containedness. Indeed, proof is immediate from Cauchy's formula

$$f(z_k) = \frac{1}{2\pi i} \int_C \frac{f(t)}{t - z_k} dt, \quad k=1, \dots, n,$$

the partial fraction decomposition

$$\frac{1}{(t - z_1) \dots (t - z_n)} = \frac{1}{z_1 - z_n} \left\{ \frac{1}{(t - z_1) \dots (t - z_{n-1})} - \frac{1}{(t - z_2) \dots (t - z_n)} \right\},$$

where  $n \geq 2$ , and the well-known recursive relation

$$f(z_1, \dots, z_n) = \frac{1}{z_1 - z_n} \left\{ f(z_1, \dots, z_{n-1}) - f(z_2, \dots, z_n) \right\}.$$

The second equality in the theorem is a direct consequence of the Cauchy formula for a function of a matrix. See, for example, [2, Chapter VII] or [5], where, in the latter, a direct, polynomial-interpolation-free approach is given.

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