# A 3/4 Differential Approximation Algorithm for Traveling Salesman Problem 

Yuki Amano ${ }^{1}$ Kazuhisa Makino ${ }^{1}$


#### Abstract

In this paper, we consider differential approximability of the traveling salesman problem (TSP). The differential approximation ratio was proposed by Demange and Paschos in 1996 as an approximation criterion that is invariant under affine transformation of the objective function. We show that TSP is $3 / 4$ differential approximable, which improves the currently best known bound $3 / 4-O(1 / n)$ due to Escoffier and Monnot in 2008, where $n$ denotes the number of vertices in the given graph.


## 1. Introduction

The traveling salesman problem (TSP) finds a shortest Hamiltonian cycle in a given complete graph with edge length, when a cycle is called Hamiltonian (also called a tour) if it visits every vertex exactly once. TSP is one of the most fundamental NP-hard optimization problems in operations research and computer science, and has been intensively studied from both practical and theoretical view points [7], [19], [21], [22]. It has a number of applications such as planning, logistics, and the manufacture of microchips [4], [11]. Because of these importance, many heuristics and exact algorithms have been proposed [3], [13], [14], [15]. From a view point of computational complexity, TSP is NP-hard, even in the Euclidean case, which includes the metric case. It is known that metric TSP is approximable with factor 1.5 [6], and inapproximable with factor 117/116 [5]. Euclidean TSP admits a polynomialtime approximation scheme (PTAS), if the dimension of the Euclidean space is bounded by a constant [1]. We note that the approximation factors (i.e., ratios) above are widely used to analyze approximation algorithms.
Let $\Pi$ be an optimization problem, and let $I$ be an instance of $\Pi$. We denote by $\operatorname{opt}(I)$ the value of an optimal solution to $I$. For an approximation algorithm $A$ for $\Pi$, we denote by $\operatorname{apx}_{A}(I)$ the value of the approximate solution computed by $A$ for the instance $I$. Let

$$
r_{A}(I)=\operatorname{apx}_{A}(I) / \operatorname{opt}(I),
$$

and define the standard approximation ratio of $A$ by $\sup _{I \in \Pi} r_{A}(I)$, where we assume that $\Pi$ is a minimization problem. Although the standard approximation ratio is well-studied and an important concept in algorithm theory, it is not invariant under affine transformation of the

[^0]objective function. Namely, if the objective function $f(x)$ is replaced by $a+b f(x)$ for some constant $a$ and $b$, which might depend on the instance $I$, the standard ratio is not preserved. For example, the vertex cover problem and the independent set problem have affinely dependent objective functions. However they have different characteristics in the standard approximation ratio. The vertex cover problem is 2 -approximable [20], while the independent set problem is inapproximable within $O\left(n^{1-\epsilon}\right)$ for any $\epsilon>0$ [9], where $n$ denotes the number of vertices in a given graph. In order to remedy to this phenomenon, Demange and Paschos [8] proposed the differential approximation ratio defined by $\sup _{I \in \Pi} \rho_{A}(I)$, where
$$
\rho_{A}(I)=\frac{\operatorname{wor}(I)-\operatorname{apx}_{A}(I)}{\operatorname{wor}(I)-\operatorname{opt}(I)}
$$
and $\operatorname{wor}(I)$ denotes the value of a worst solution to $I$. Note that for any instance $I$ of $\Pi$
$$
\operatorname{apx}_{A}(I)=\rho_{A}(I) \operatorname{opt}(I)+\left(1-\rho_{A}(I)\right) \operatorname{wor}(I) .
$$

Thus we have $0 \leq \rho_{A}(I) \leq 1$ and the larger $\rho_{A}(I)$ implies the better approximation for the instance $I$. Moreover, by definition, the differential approximation ratio remains invariant under affine transformation of the objective function. For this, it has been recently attracted much attention in approximation algorithm [2]. It is known [17] that TSP, metric TSP, max TSP, and max metric TSP are affinely equivalent, i.e., their objective functions are transferred to each other by affine transformations, where max TSP is the problem to find a longest Hamiltonian cycle and max metric TSP is max TSP, in which the input weighted graph satisfies the metric condition. Therefore, these problems have the identical differential approximation ratio.

Hassin and Khuller [12] first studied differential approximability of TSP, and showed that it is $2 / 3$-differential approximable. Escoffier and Monnot [10] improved it to
$3 / 4-O(1 / n)$, where $n$ denotes the number of vertices of a given graph. Monnot et al. [16], [18] showed that TSP is $3 / 4$-differential approximable if each edge length is restricted to one or two.
In this paper, we show that TSP is $3 / 4$-differential approximable, which improves the currently best known results [10], [16], [18]. Our algorithm is based on an idea in [10] for the case in which a given graph $G$ has an even number of vertices and a triangle (i.e., cycle with 3 edges) is contained in a minimum weighted 2 -factor of $G$. Their algorithm first computes minimum weighted 1 - and 2 -factors of a given graph, modify them to four path covers $P_{i}$ (for $i=1, \ldots, 4$ ), and then extend each path cover $P_{i}$ to a tour by adding edge set $F_{i}$ to it in such a way that at least one of the tours guarantees $3 / 4$-differential approximation ratio. Here the definitions of factor and path cover can be found in Section 2. We generalize their idea to the general even case. Note that $\bigcup_{i=1}^{4} F_{i}$ in their algorithm always forms a tour, where in general it does not. We show that there exists a way to construct path covers such that the length of $\bigcup_{i=1}^{4} F_{i}$ is at most the worst tour length. Our algorithm for odd case is much more involved. For each path with three edges, we first construct a 2 -factor and two path covers of a given graph which has minimum length among all these which completely and partially contains the path, modify them to eight path covers, and then extend each path cover to a tour, in such a way that at least one of the eight tours guarantees $3 / 4$-differential approximation ratio.
The rest of the paper is organized as follows. In Section 2 , we define basic concepts of graphs and discuss some properties on 2-matchings, which will be used in the subsequent sections. In Sections 3 and 4, we provide an approximation algorithms for TSP in which a given graph $G$ has even and odd numbers of vertices, respectively.

## 2. Preliminary

Let $G=(V, E)$ be an undirected graph, where $n$ and $m$ denote the number of vertices and edges in $G$, respectively. In this paper, we assume that a given graph $G$ of TSP is complete, i.e., $E=\binom{V}{2}$, and it has an edge length function $\ell: E \rightarrow \mathbb{R}_{+}$, where $\mathbb{R}_{+}$denotes the set of nonnegative reals. For a set $F \subseteq E$, let $V(F)$ denote the set of vertices with incident edges in $F$, i.e., $V(F)=\{v \in V \mid \exists(v, w) \in F\}$. A set $F \subseteq E$ is called spanning if $V(F)=V$, and acyclic if $F$ contains no cycle. For a positive integer $k$, a set $F \subseteq E$ is called a $k$-matching (resp., $k$-factor) if each vertex has at most (resp., exactly) $k$ incident edges in $F$. Here 1-matching is simply called a matching. Note that an acyclic 2-matching $F$ corresponds to a family of vertex-disjoint paths denoted by $\mathcal{P}(F) \subseteq 2^{E}$. A 2 -matching is called a path cover if it is spanning and acyclic. For a set $F \subseteq E, V_{1}(F)$ and $V_{2}(F)$ respectively denote the sets of vertices with one and two incident edges in $F$. For a set $F \subseteq E$ and a vertex $v \in V$, let $\delta_{F}(v)=\{e \in F \mid e$ is incident to $v\}$.
Definition 1. A pair of spanning 2-matchings $(S, T)$ is called valid if it satisfies the following three conditions:


Fig. 1: A valid pair ( $S, T$ ) of spanning 2-matchings.
(i) $T$ is acyclic.
(ii) $\delta_{S}(v)=\delta_{T}(v)$ for any $v \in V_{2}(S) \cap V_{2}(T)$.
(iii) $V(C) \neq V(P)$ for any cycle $C \subseteq S$ and any path $P \subseteq \mathcal{P}(T)$.

Lemma 2. Let $(S, T)$ be a valid pair of spanning 2matchings. If $S$ contains a cycle $C$, then $C$ contains two edges $e_{i}$ for $i=1,2$ such that $S_{i}=S \backslash\left\{e_{i}\right\}$ and $T_{i}=S \cup\left\{e_{i}\right\}$ satisfy the following three conditions:

$$
\begin{align*}
& \left(S_{i}, T_{i}\right) \text { is valid for } i=1,2 .  \tag{3}\\
& V_{1}\left(S_{i}\right) \cup V_{1}\left(T_{i}\right)=V_{1}(S) \cup V_{1}(T) \text { and }  \tag{4}\\
& \quad V_{1}\left(S_{i}\right) \cap V_{1}\left(T_{i}\right)=V_{1}(S) \cap V_{1}(T) \text { for } i=1,2 . \\
& \mathcal{P}(T) \text { contains a path } P \text { such that } P \cup\left\{e_{1}\right\} \text { and }  \tag{5}\\
& \quad P \cup\left\{e_{2}\right\} \text { are both paths. }
\end{align*}
$$

Note that ( $S_{1}, T_{1}$ ) and ( $S_{2}, T_{2}$ ) in Lemma 2 satisfy
$S_{i} \cup T_{i}=S \cup T$ and $S_{i} \cap T_{i}=S \cap T$ for $i=1,2$,
which immediately implies

$$
\begin{equation*}
\ell\left(S_{i}\right)+\ell\left(T_{i}\right)=\ell(S)+\ell(T) \text { for } i=1,2, \tag{7}
\end{equation*}
$$

where $\ell(F)=\sum_{e \in F} \ell(e)$ for a set $F \subseteq E$.
Figure 1 shows a valid pair of spanning 2-matchings and two edges $e_{c}$ and $e_{d}$ in $C$ that satisfy the three conditions of Lemma 2.

## 3. Approximation for even instances

In this section, we construct an approximation algorithm for TSP in which a given graph has an even number of vertices. Our algorithm first construct four path covers from minimum weighted 1- and 2 -factors of a given graph $G$, and then extend each path cover to a tour in such a way that at least one of the tours guarantees $3 / 4$-differential approximation ratio.

Let us first explain the procedure FourPathCovers where it can be found in Fig. 2. Let $(S, T)$ be a valid pair of spanning 2 -matchings of $(G, \ell)$ such that $S$ is a 2 -factor. The procedure computes from $(S, T)$ four path covers $S_{1}, S_{2}$, $T_{1}$, and $T_{2}$ that satisfies (4), (6), $V_{1}\left(S_{i}\right)$ and $V_{1}\left(T_{i}\right)$ is a partition of $V_{1}(T)$ for $i=1,2$, i.e.,

$$
\begin{align*}
& V_{1}\left(S_{i}\right) \cup V_{1}\left(T_{i}\right)=V_{1}(T) \text { and }  \tag{8}\\
& \quad V_{1}\left(S_{i}\right) \cap V_{1}\left(T_{i}\right)=\emptyset \text { for } i=1,2,
\end{align*}
$$

and
there exist $e_{1}, e_{2} \in E$ and $P \in \mathcal{P}\left(T_{1} \cap T_{2}\right)$ such that $T_{1} \backslash T_{2}=\left\{e_{1}\right\}, T_{2} \backslash T_{1}=\left\{e_{2}\right\}$, and (9) $P \cup\left\{e_{1}\right\}$ and $P \cup\left\{e_{2}\right\}$ are both paths.

In Fig. 2 we apply Procedure FourPathCovers to ( $S, T$ ) in Fig. 1.
Lemma 3. For a graph $G=(V, E)$, let $(S, T)$ be a valid pair of spanning 2 -matchings such that $S$ has a cycle. Then Procedure FourPathCovers returns four path covers $S_{1}$, $S_{2}, T_{1}$, and $T_{2}$ that satisfy (4), (6), and (9). Furthermore, if $S$ is addition a 2-factor of $G$, then the four path covers satisfy (8).
Note that $(S, T)$ is a valid and $V_{1}(T)=V$, if $S$ and $T$ are 2 - and 1-factors of $G$, respectively.
Let $S$ and $T$ be 2- and 1-factors of $G$, respectively. Note that our algorithm explain later makes use of minimum weighted 2-factor $S$ and 1-factor $T$ of ( $G, \ell$ ) which can be computed from $(G, \ell)$ in polynomial time. We assume that $S$ is not a tour of $G$, i.e., $S$ contains at least two cycles, since otherwise, $S$ itself is an optimal tour. Let $S_{1}$, $S_{2}, T_{1}$, and $T_{2}$ be path covers returned by Procedure FourPathCover $(S, T)$.
Let us then show how to construct edge sets $A_{1}, A_{2}, B_{1}$, and $B_{2}$, such that

$$
\begin{align*}
& S_{i} \cup A_{i} \text { is tour }(\text { for } i=1,2),  \tag{10}\\
& T_{i} \cup B_{i} \text { is tour }(\text { for } i=1,2) \text {, and }  \tag{11}\\
& \ell\left(A_{1}\right)+\ell\left(A_{2}\right)+\ell\left(B_{1}\right)+\ell\left(B_{2}\right) \leq \operatorname{wor}(G, \ell), \tag{12}
\end{align*}
$$

where $\operatorname{wor}(G, \ell)$ denotes the length of a longest tour of (G, ).
Let $e_{1}=\left(p_{1}, p_{2}\right)$ and $e_{2}=\left(p_{3}, p_{4}\right)$ be edges in Lemma 3. Since $e_{1}$ and $e_{2}$ are chosen from a cycle $C$ and satisfy (9), we can assume that $p_{1} \neq p_{3}, p_{4}$ and $p_{4} \neq p_{1}, p_{2}$, where $p_{2}=p_{3}$ might hold. We note that $\mathcal{P}\left(S_{1}\right) \backslash \mathcal{P}\left(S_{2}\right)$ consists of a ( $p_{1}, p_{2}$ )-path $P_{1}=C \backslash\left\{e_{1}\right\}$, and $\mathcal{P}\left(S_{2}\right) \backslash \mathcal{P}\left(S_{1}\right)$ consists of a ( $p_{3}, p_{4}$ )-path $P_{2}=C \backslash\left\{e_{2}\right\}$.
Let $Q_{i}(i=1, \ldots, k)$ denote vertex-disjoint $\left(x_{i}, y_{i}\right)$-paths such that $\left\{Q_{1}, \ldots, Q_{k}\right\}=\mathcal{P}\left(S_{1}\right) \cap \mathcal{P}\left(S_{2}\right)$ and $x_{1}$ and $y_{1}$ satisfy

$$
\begin{equation*}
\ell\left(p_{2}, x_{1}\right)+\ell\left(p_{3}, y_{1}\right) \leq \ell\left(p_{2}, y_{1}\right)+\ell\left(p_{3}, x_{1}\right) . \tag{13}
\end{equation*}
$$

Define $A_{1}$ and $A_{2}$ by

$$
\begin{align*}
A_{1}= & \left\{\left(p_{2}, x_{1}\right)\right\} \cup\left\{\left(y_{k}, p_{1}\right)\right\} \\
& \cup\left\{\left(y_{i}, x_{i+1}\right) \mid i=1, \ldots, k-1\right\}  \tag{14}\\
A_{2}= & \left\{\left(p_{3}, y_{1}\right)\right\} \cup\left\{\left(x_{k}, p_{4}\right)\right\} \\
& \cup\left\{\left(x_{i}, y_{i+1}\right) \mid i=1, \ldots, k-1\right\} .
\end{align*}
$$

Figure 3 shows two edge sets $A_{1}$ and $A_{2}$ for $S_{1}$ and $S_{2}$ in Fig. 2.

Lemma 4. Two edge sets $A_{1}$ and $A_{2}$ defined in (14) satisfy (10) and $A_{1} \cap A_{2}=\emptyset$, and $A_{1} \cup A_{2}$ consists of (i) a $\left(p_{1}, p_{4}\right)$-path if $p_{2}=p_{3}$ and either (ii) vertex-disjoint $\left(p_{1}, p_{3}\right)$ - and ( $p_{2}, p_{4}$ )-paths or (iii) vertex-disjoint ( $p_{1}, p_{2}$ )and $\left(p_{3}, p_{4}\right)$-paths if $p_{2} \neq p_{3}$.
Let us next construct $B_{1}$ and $B_{2}$. Let $O_{i}(i=1, \ldots, d)$ denote vertex-disjoint $\left(z_{i}, w_{i}\right)$-paths such that $\left\{O_{1}, \ldots, O_{d}\right\}=$ $\mathcal{P}\left(T_{1}\right) \cap \mathcal{P}\left(T_{2}\right)$. Note that $\mathcal{P}\left(T_{1}\right) \cap \mathcal{P}\left(T_{2}\right)=\emptyset$ (i.e., $d=0$ ) might hold. We separately consider the following four cases.
(1) $p_{2}=p_{3}, p_{1} \neq p_{4}$, and $\mathcal{P}\left(T_{1} \cap T_{2}\right)$ contains a $\left(p_{1}, p_{4}\right)$ path.
(2) $p_{2}=p_{3}, p_{1} \neq p_{4}$, and $\mathcal{P}\left(T_{1} \cap T_{2}\right)$ contain no $\left(p_{1}, p_{4}\right)$ path.
(3) $p_{2} \neq p_{3}, p_{1} \neq p_{4}$, and $\mathcal{P}\left(T_{1} \cap T_{2}\right)$ contains $\left(p_{1}, p_{4}\right)$ - and ( $p_{2}, p_{3}$ )-paths.
(4) $p_{2} \neq p_{3}, p_{1} \neq p_{4}$, and $\mathcal{P}\left(T_{1} \cap T_{2}\right)$ contains a $\left(p_{2}, p_{3}\right)$ path and no ( $p_{1}, p_{4}$ )-path.
Here we recall that $e_{1}=\left(p_{1}, p_{2}\right)$ and $e_{2}=\left(p_{3}, p_{4}\right)$ satisfy Lemma 3.

Case 1: Let $R_{1}$ denote a ( $p_{1}, p_{4}$ )-path in $\mathcal{P}\left(T_{1} \cap T_{2}\right)$, and for some vertex $q_{2}$, let $R_{2}$ denote ( $p_{2}, q_{2}$ )-path in $\mathcal{P}\left(T_{1} \cap T_{2}\right)$. Then, we have

$$
\begin{aligned}
& \mathcal{P}\left(T_{1}\right)=\left\{O_{1}, \ldots, O_{d}\right\} \cup\left\{R_{1} \cup\left\{e_{1}\right\} \cup R_{2}\right\} \\
& \mathcal{P}\left(T_{2}\right)=\left\{O_{1}, \ldots, O_{d}\right\} \cup\left\{R_{1} \cup\left\{e_{2}\right\} \cup R_{2}\right\},
\end{aligned}
$$

where $R_{1} \cup\left\{e_{1}\right\} \cup R_{2}$ and $R_{1} \cup\left\{e_{2}\right\} \cup R_{2}$ are $\left(p_{4}, q_{2}\right)$ - and ( $p_{1}, q_{2}$ )-paths, respectively. Define $B_{1}$ and $B_{2}$ by

$$
\begin{align*}
& B_{1}= \begin{cases}\left\{\left(q_{2}, p_{4}\right)\right\} & \text { if } d=0 \\
\left\{\left(q_{2}, z_{1}\right)\right\} \cup\left\{\left(w_{d}, p_{4}\right)\right\} & \text { if } d \geq 1 \\
\cup\left\{\left(w_{i}, z_{i+1}\right) \mid i=1, \ldots, d-1\right\}\end{cases}  \tag{15}\\
& B_{2}= \begin{cases}\left\{\left(q_{2}, p_{1}\right)\right\} & \text { if } d=0 \\
\left\{\left(q_{2}, w_{1}\right)\right\} \cup\left\{\left(z_{d}, p_{1}\right)\right\} & \text { if } d \geq 1 .\end{cases}
\end{align*}
$$

By definition, two edge sets $B_{1}$ and $B_{2}$ satisfy (11) and $B_{1} \cap B_{2}=\emptyset$, and $B_{1} \cup B_{2}$ consists of a ( $p_{1}, p_{4}$ )-path

Case 2: For some vertices $q_{1}, q_{2}$ and $q_{4}$, let $R_{1}, R_{2}$, and $R_{4}$ respectively denote $\left(p_{1}, q_{1}\right)$-, $\left(p_{2}, q_{2}\right)$-, and ( $p_{4}, q_{4}$ )-paths in $\mathcal{P}\left(T_{1} \cap T_{2}\right)$. Then, we have

$$
\begin{aligned}
& \mathcal{P}\left(T_{1}\right)=\left\{O_{1}, \ldots, O_{d}\right\} \cup\left\{R_{4}, R_{1} \cup\left\{e_{1}\right\} \cup R_{2}\right\} \\
& \mathcal{P}\left(T_{2}\right)=\left\{O_{1}, \ldots, O_{d}\right\} \cup\left\{R_{1}, R_{4} \cup\left\{e_{2}\right\} \cup R_{2}\right\},
\end{aligned}
$$

where $R_{1} \cup\left\{e_{1}\right\} \cup R_{2}$ and $R_{4} \cup\left\{e_{2}\right\} \cup R_{2}$ are $\left(q_{1}, q_{2}\right)$ - and ( $q_{4}, q_{2}$ )-paths, respectively. Define $B_{1}$ and $B_{2}$ by

$$
\begin{align*}
& B_{1}= \begin{cases}\left\{\left(q_{2}, q_{4}\right),\left(p_{4}, q_{1}\right)\right\} & \text { if } d=0 \\
\left\{\left(q_{2}, z_{1}\right)\right\} \cup\left\{\left(w_{d}, q_{4}\right),\left(p_{4}, q_{1}\right)\right\} & \text { if } d \geq 1 \\
\cup\left\{\left(w_{i}, z_{i+1}\right) \mid i=1, \ldots, d-1\right\}\end{cases}  \tag{16}\\
& B_{2}= \begin{cases}\left\{\left(q_{2}, q_{1}\right),\left(p_{1}, q_{4}\right)\right\} & \text { if } d=0 \\
\left\{\left(q_{2}, w_{1}\right)\right\} \cup\left\{\left(z_{d}, q_{1}\right),\left(p_{1}, q_{4}\right)\right\} & \text { if } d \geq 1 .\end{cases}
\end{align*}
$$

Similarly to Case 1, we have (11), $B_{1} \cap B_{2}=\emptyset$, and $B_{1} \cup B_{2}$

## Procedure FourPathCovers $(S, T)$

$/^{*}(S, T)$ is a valid pair of spanning 2 -matchings such that $S$ has a cycle. The procedure returns 4 path covers $S_{1}, S_{2}, T_{1}$, and $T_{2}$ that satisfies (4), (6), and (9).*/

```
    if \(S\) has exactly one cycle then
        Take two edges \(e_{1}\) and \(e_{2}\) in Lemma 2.
    else /* \(S\) has at least two cycles. */
        Take an edge \(e_{1}\) in Lemma 2.
        return FourPathCovers \(\left(S \backslash\left\{e_{1}\right\}, T \cup\left\{e_{1}\right\}\right)\)
    end if
```

        return \(S_{1}=S \backslash\left\{e_{1}\right\}, T_{1}=T \cup\left\{e_{1}\right\}, S_{2}=S \backslash\left\{e_{2}\right\}\), and \(T_{2}=T \cup\left\{e_{2}\right\}\)
    
$S_{1}$

$T_{1}$

$S_{2}$

$T_{2}$

Fig. 2: Two pairs $\left(S_{1}, T_{1}\right)$ and $\left(S_{2}, T_{2}\right)$ computed by Procedure FourPathCovers for a valid pair $(S, T), e_{1}^{(1)}=e_{a}, e_{1}^{(2)}=e_{b}$, $e_{1}^{(3)}=e_{c}$ and $e_{2}^{(3)}=e_{d}$ in Fig. 1, where $e_{i}^{(j)}$ denotes the edge chosen as $e_{i}$ in the $j$-th round of the procedure.
consists of a $\left(p_{1}, p_{4}\right)$-path.
Case 3: Let $R_{1}$ and $R_{2}$ respectively denote ( $p_{1}, p_{4}$ )- and ( $p_{2}, p_{3}$ )-paths in $\mathcal{P}\left(T_{1} \cap T_{2}\right)$. Then, we have

$$
\begin{aligned}
& \mathcal{P}\left(T_{1}\right)=\left\{O_{1}, \ldots, O_{d}\right\} \cup\left\{R_{1} \cup\left\{e_{1}\right\} \cup R_{2}\right\} \\
& \mathcal{P}\left(T_{2}\right)=\left\{O_{1}, \ldots, O_{d}\right\} \cup\left\{R_{1} \cup\left\{e_{2}\right\} \cup R_{2}\right\},
\end{aligned}
$$

where $R_{1} \cup\left\{e_{1}\right\} \cup R_{2}$ and $R_{1} \cup\left\{e_{2}\right\} \cup R_{2}$ are $\left(p_{3}, p_{4}\right)$ - and ( $p_{1}, p_{2}$ )-paths, respectively. Define $B_{1}$ and $B_{2}$ by

$$
\begin{align*}
& B_{1}= \begin{cases}\left\{\left(p_{3}, p_{4}\right)\right\} & \text { if } d=0 \\
\left\{\left(p_{3}, z_{1}\right)\right\} \cup\left\{\left(w_{d}, p_{4}\right)\right\} & \text { if } d \geq 1 \\
\cup\left\{\left(w_{i}, z_{i+1}\right) \mid i=1, \ldots, d-1\right\}\end{cases}  \tag{17}\\
& B_{2}= \begin{cases}\left\{\left(p_{2}, p_{1}\right)\right\} & \text { if } d=0 \\
\left\{\left(p_{2}, w_{1}\right)\right\} \cup\left\{\left(z_{d}, p_{1}\right)\right\} & \text { if } d \geq 1 .\end{cases}
\end{align*}
$$

Similarly to the previous cases, we have (11), $B_{1} \cap B_{2}=\emptyset$, and $B_{1} \cup B_{2}$ consists of either vertex-disjoint $\left(p_{1}, p_{2}\right)$ - and $\left(p_{3}, p_{4}\right)$-paths or vertex-disjoint $\left(p_{1}, p_{3}\right)$ - and ( $\left.p_{2}, p_{4}\right)$-paths.

Case 4: Let $R_{2}$ denote ( $p_{2}, p_{3}$ )-path in $\mathcal{P}\left(T_{1} \cap T_{2}\right)$, and for some vertices $q_{1}$ and $q_{4}$, let $R_{1}$ and $R_{4}$ respectively denote ( $p_{1}, q_{1}$ )- and ( $p_{4}, q_{4}$ )-paths in $\mathcal{P}\left(T_{1} \cap T_{2}\right)$. Then, we have

$$
\begin{aligned}
& \mathcal{P}\left(T_{1}\right)=\left\{O_{1}, \ldots, O_{d}\right\} \cup\left\{R_{4}, R_{1} \cup\left\{e_{1}\right\} \cup R_{2}\right\} \\
& \mathcal{P}\left(T_{2}\right)=\left\{O_{1}, \ldots, O_{d}\right\} \cup\left\{R_{1}, R_{4} \cup\left\{e_{2}\right\} \cup R_{2}\right\},
\end{aligned}
$$

where $R_{1} \cup\left\{e_{1}\right\} \cup R_{2}$ and $R_{4} \cup\left\{e_{2}\right\} \cup R_{2}$ are $\left(q_{1}, p_{3}\right)$ - and ( $q_{4}, p_{2}$ )-paths, respectively. Define $B_{1}$ and $B_{2}$ by

$$
\begin{align*}
& B_{1}= \begin{cases}\left\{\left(p_{3}, q_{4}\right),\left(p_{4}, q_{1}\right)\right\} & \text { if } d=0 \\
\left\{\left(p_{3}, z_{1}\right)\right\} \cup\left\{\left(w_{d}, q_{4}\right),\left(p_{4}, q_{1}\right)\right\} & \text { if } d \geq 1 \\
\cup\left\{\left(w_{i}, z_{i+1}\right) \mid i=1, \ldots, d-1\right\}\end{cases} \\
& B_{2}= \begin{cases}\left\{\left(p_{2}, q_{1}\right),\left(p_{1}, q_{4}\right)\right\} & \text { if } d=0 \\
\left\{\left(p_{2}, w_{1}\right)\right\} \cup\left\{\left(z_{d}, q_{1}\right),\left(p_{1}, q_{4}\right)\right\} & \text { if } d \geq 1 .\end{cases} \tag{18}
\end{align*}
$$

Similarly to the previous cases, we have (11), $B_{1} \cap B_{2}=\emptyset$, and $B_{1} \cup B_{2}$ consists of either vertex-disjoint $\left(p_{1}, p_{2}\right)$ - and $\left(p_{3}, p_{4}\right)$-paths or vertex-disjoint ( $p_{1}, p_{3}$ )- and ( $p_{2}, p_{4}$ )-paths.

In summary, we have the following lemma.
Lemma 5. Two edge sets $B_{1}$ and $B_{2}$ defined as above satisfy (11) and $B_{1} \cap B_{2}=\emptyset$, and $B_{1} \cup B_{2}$ consists of (i) $a\left(p_{1}, p_{4}\right)$-path if $p_{2}=p_{3}$ and either (ii) vertex-disjoint $\left(p_{1}, p_{2}\right)$ - and ( $p_{3}, p_{4}$ )-paths or (iii) vertex-disjoint $\left(p_{1}, p_{3}\right)$ and $\left(p_{2}, p_{4}\right)$-paths if $p_{2} \neq p_{3}$.
Figure 4 shows two edge sets $B_{1}$ and $B_{2}$ for path covers $T_{1}$ and $T_{2}$ in Fig. 2. Furthermore, $A_{i}$ and $B_{i}(i=1,2)$ satisfy the following properties.
Lemma 6. Let $A_{1}, A_{2}, B_{1}$, and $B_{2}$ be defined as above. Then they are all pairwise disjoint, and $C=A_{1} \cup A_{2} \cup$ $B_{1} \cup B_{2}$ is a 2-factor, consisting of either one or two cycles. Furthermore, there exists a tour $H$ of $G$ such that $\ell(H) \geq \ell(C)$.

We are now ready to describe our approximation algorithm.
Theorem 7. For a complete graph $G=(V, E)$ with


Fig. 3: Two edge sets $A_{1}$ and $A_{2}$ for path covers $S_{1}$ and $S_{2}$ in Fig. 2.


Fig. 4: Two edge sets $B_{1}$ and $B_{2}$ for path covers $T_{1}$ and $T_{2}$ in Fig. 2.
an even number of vertices and an edge length function $\ell: E \rightarrow R_{+}$, Algorithm TourEven computes a 3/4differential approximate tour of $(G, \ell)$ in polynomial time.

Proof. We show that Algorithm TourEven outputs a 3/4differential approximate tour $T_{\mathrm{apx}}$ in polynomial time. If a minimum weighted 2 -factor $S$ of $(G, \ell)$ computed in the algorithm is a tour, then clearly $T_{\mathrm{apx}}=S$ is an optimal tour. On the other hand, if $S$ is not a tour, then we have

$$
\begin{aligned}
& 4 \ell\left(T_{\mathrm{apx}}\right) \\
& \quad \leq \ell\left(S_{1} \cup A_{1}\right)+\ell\left(S_{2} \cup A_{2}\right)+\ell\left(T_{1} \cup B_{1}\right)+\ell\left(T_{2} \cup B_{2}\right) \\
& \quad=2(\ell(S)+\ell(T))+\ell\left(A_{1}\right)+\ell\left(A_{2}\right)+\ell\left(B_{1}\right)+\ell\left(B_{2}\right) \\
& \quad \leq 3 \operatorname{opt}(G, \ell)+\operatorname{wor}(G, \ell),
\end{aligned}
$$

where the first equality follows from Lemmas 4,5 , and 6 , and the last inequality follows from Lemma 6 , and $\ell(S) \leq$ $\operatorname{opt}(G, \ell)$, and $2 \ell(T) \leq \operatorname{opt}(G, \ell)$. Thus $T_{\text {apx }}$ is a $3 / 4-$ differential approximate tour. Note that minimum weighted 1 - and 2 -factors can be computed in polynomial time, and $A_{i}$ and $B_{i}(i=1,2)$ can be computed in polynomial time. Thus Algorithm TourEven is polynomial, which completes the proof.

Before concluding the section, let us remark that 3/4differential approximability is known for graph with an even number of vertices [10]. Different from the algorithm in [10], ours is constructed in a uniform framework, which can further be extended to the odd case.

## 4. Approximation for odd instances

In this section, we construct an approximation algorithm for TSP with an odd number of vertices. Our algorithm is much more involved than the even case. It first guesses a path $P$ with three edges in an optimal tour, constructs eight path covers based on $P$, and extend each path cover to a tour in such a way that at least one of the eight tours guarantees $3 / 4$-differential approximation ratio.

More precisely, for each path $P$ with three edges, say, $P=\left\{\left(v_{1}, v_{2}\right),\left(v_{2}, v_{3}\right),\left(v_{3}, v_{4}\right)\right\}$ with all $v_{i}$ 's distinct, let $S$ be a minimum weighted 2 -factor among those containing $P$, let $T$ be a minimum weighted path cover among those satisfying $\left(v_{1}, v_{2}\right),\left(v_{2}, v_{3}\right) \in T$ and $V_{1}(T)=V \backslash\left\{v_{2}\right\}$, and let $T^{\prime}$ be a minimum weighted path cover among those satisfying $\left(v_{2}, v_{3}\right),\left(v_{3}, v_{4}\right) \in T^{\prime}$ and $V_{1}\left(T^{\prime}\right)=V \backslash\left\{v_{3}\right\}$. Assume that $S$ is not a tour, i.e., it contains at least two cycles, since otherwise, is optimal, and hence ensures $3 / 4$ differential approximability if some optimal tour contains $P$. We note that $(S, T)$ and $\left(S, T^{\prime}\right)$ are both valid pairs of spanning 2-matchings. We apply Procedure FourPathCovers to them, but not arbitrarily. Let us specify two cycles $C^{*}$ and $C^{* *}$ in $S$ such that $P \subseteq C^{*}$ and $P \cap C^{* *}=\emptyset$. We define two vertices $v_{0}$ and $v_{5}$ in $V\left(C^{*}\right)$ such that $v_{0} \neq v_{2}$, $v_{5} \neq v_{3}$, and $\left(v_{0}, v_{1}\right),\left(v_{4}, v_{5}\right) \in C^{*}$. By definition $v_{0}=v_{4}$ and $v_{5}=v_{1}$ hold if $\left|C^{*}\right|=4$. Furthermore, we define two edges $f$ and $f^{\prime}$ in $C^{* *}$ that satisfy the properties in the next

```
Algorithm TourEven
Input: A complete graph \(G=(V, E)\) with even \(|V|\), and an edge length function \(\ell: E \rightarrow \mathbb{R}_{+}\).
Output: A tour \(T_{\text {apx }}\) in \(G\).
    Compute minimum weighted 2-factor \(S\) and 1-factor \(T\) of \((G, \ell)\).
    if \(S\) is a tour then
        \(T_{\text {apx }}:=S\)
    else
        \(S_{1}, T_{1}, S_{2}, T_{2}:=\) FourPathCovers \((S, T)\).
        Compute edge sets \(A_{1}, A_{2}, B_{1}, B_{2}\) defined in (14), (15), (16), (17), and (18).
        \(\mathcal{T}:=\left\{S_{1} \cup A_{1}, S_{2} \cup A_{2}, T_{1} \cup B_{1}, T_{2} \cup B_{2}\right\}\).
        \(T_{\mathrm{apx}}:=\underset{T \in \mathcal{T}}{\operatorname{argmin}} \ell(T)\).
    end if
```

    Outputs \(T_{\mathrm{apx}}\) and halt.
    
## lemma.

Lemma 8. Let $C^{* *}, T$ and $T^{\prime}$ be defined as above. Then there exist two edges $f \in C^{* *} \backslash T$ and $f^{\prime} \in C^{* *} \backslash T^{\prime}$ such that
(i) they have a common endpoint $q$, and
(ii) $T \cup\{f\}$ and $T^{\prime} \cup\left\{f^{\prime}\right\}$ are path covers.

We note that $f$ and $f^{\prime}$ in Lemma 8 might be identical, and (ii) in Lemma 8 implies that two pairs $(S \backslash\{f\}, T \cup\{f\})$ and $\left(S \backslash\left\{f^{\prime}\right\}, T^{\prime} \cup\left\{f^{\prime}\right\}\right)$ are valid.
Our algorithm uses Procedure FourPathCovers for $(S, T)$ defined as above in such a way that edge $e_{1}=f$ is chosen in the first round and two edges $e_{1}=\left(v_{3}, v_{4}\right)$ and $e_{2}=\left(v_{0}, v_{1}\right)$ are chosen in the last round. Similarly, our algorithm uses Procedure FourPathCovers for ( $S, T^{\prime}$ ) defined as above in such a way that edge $e_{1}=f^{\prime}$ is chosen in the first round and two edges $e_{1}=\left(v_{1}, v_{2}\right)$ and $e_{2}=\left(v_{4}, v_{5}\right)$ are chosen in the last round. Let $S_{1}, T_{1}, S_{2}$, and $T_{2}$ be four path covers obtained by Procedure FourPathCover $(S, T)$, and let $S_{1}^{\prime}, T_{1}^{\prime}, S_{2}^{\prime}$, and $T_{2}^{\prime}$ be four path covers returned by Procedure FourPathCover $\left(S, T^{\prime}\right)$.
Lemma 9. Let $S, T, S_{i}$, and $T_{i}(i=1,2)$ be defined as above. Then $S_{1}, S_{2}, T_{1}$, and $T_{2}$ are path covers such that

$$
\begin{align*}
& S_{i} \cup T_{i}=S \cup T \text { and } S_{i} \cap T_{i}=S \cap T \text { for } i=1,2,  \tag{19}\\
& V_{1}\left(S_{i}\right) \cup V_{1}\left(T_{i}\right)=V \backslash\left\{v_{2}\right\} \text { and } \\
& \quad V_{1}\left(S_{i}\right) \cap V_{1}\left(T_{i}\right)=\emptyset \text { for } i=1,2,  \tag{20}\\
& T_{1} \backslash T_{2}=\left\{\left(v_{3}, v_{4}\right)\right\}, T_{2} \backslash T_{1}=\left\{\left(v_{0}, v_{1}\right)\right\}, \text { and } \\
& \quad\left\{\left(v_{1}, v_{2}\right),\left(v_{2}, v_{3}\right)\right\} \in \mathcal{P}\left(T_{1} \cap T_{2}\right), \text { and }  \tag{21}\\
& q \in V_{1}\left(S_{1}\right) \cap V_{1}\left(S_{2}\right), \tag{22}
\end{align*}
$$

where $v_{i} \in V\left(C^{*}\right)(i=0, \ldots, 4)$ are defined as above and $q$ is a common endpoint of $f$ and $f^{\prime}$ in Lemma 8.
Similarly, we have the following lemma.
Lemma 10. Let $S, T^{\prime}, S_{i}^{\prime}$, and $T_{i}^{\prime}(i=1,2)$ be defined as above. Then $S_{1}^{\prime}, S_{2}^{\prime}, T_{1}^{\prime}$, and $T_{2}^{\prime}$ are path covers such that
$S_{i}^{\prime} \cup T_{i}^{\prime}=S \cup T^{\prime}$ and $S_{i}^{\prime} \cap T_{i}^{\prime}=S \cap T^{\prime}$ for $i=1,2$,
$V_{1}\left(S_{i}^{\prime}\right) \cup V_{1}\left(T_{i}^{\prime}\right)=V \backslash\left\{v_{3}\right\}$ and
$V_{1}\left(S_{i}^{\prime}\right) \cap V_{1}\left(T_{i}^{\prime}\right)=\emptyset$ for $i=1,2$,

$$
\begin{align*}
& T_{1}^{\prime} \backslash T_{2}^{\prime}=\left\{\left(v_{1}, v_{2}\right)\right\}, T_{2}^{\prime} \backslash T_{1}^{\prime}=\left\{\left(v_{4}, v_{5}\right)\right\}, \text { and } \\
& \quad\left\{\left(v_{2}, v_{3}\right),\left(v_{3}, v_{4}\right)\right\} \in \mathcal{P}\left(T_{1}^{\prime} \cap T_{2}^{\prime}\right), \text { and }  \tag{25}\\
& q \in V_{1}\left(S_{1}^{\prime}\right) \cap V_{1}\left(S_{2}^{\prime}\right), \tag{26}
\end{align*}
$$

where $v_{i} \in V\left(C^{*}\right)(i=1, \ldots, 5)$ are defined as above and $q$ is a common endpoint of $f$ and $f^{\prime}$ in Lemma 8.

We can construct edge sets $A_{i}^{(\prime)}$ and $B_{i}^{(\prime)}$ (for $i=1,2$ ), such that

$$
\begin{align*}
& \left.S_{i} \cup A_{i} \text { is tour (for } i=1,2\right),  \tag{27}\\
& \left.T_{i} \cup B_{i} \text { is tour (for } i=1,2\right),  \tag{28}\\
& \left.S_{i}^{\prime} \cup A_{i}^{\prime} \text { is tour (for } i=1,2\right),  \tag{29}\\
& \left.T_{i}^{\prime} \cup B_{i}^{\prime} \text { is tour (for } i=1,2\right) \text {, and }  \tag{30}\\
& \ell\left(A_{1}\right)+\ell\left(A_{2}\right)+\ell\left(B_{1}\right)+\ell\left(B_{2}\right)+\ell\left(A_{1}^{\prime}\right)+\ell\left(A_{2}^{\prime}\right) \\
& \quad+\ell\left(B_{1}^{\prime}\right)+\ell\left(B_{2}^{\prime}\right) \leq 2 \operatorname{wor}(G, \ell)-2 \ell\left(v_{2}, v_{3}\right), \tag{31}
\end{align*}
$$

where $\operatorname{wor}(G, \ell)$ denotes the length of a longest tour of $(G, \ell)$.

We are now ready to describe our approximation algorithm, called TourOdd.
Before analyzing Algorithm TourOdd, let us evaluate $\ell(S), \ell(T)$ and $\ell\left(T^{\prime}\right)$.
Lemma 11. For a path $P=\left\{\left(v_{1}, v_{2}\right),\left(v_{2}, v_{3}\right),\left(v_{3}, v_{4}\right)\right\}$, let $S, T$ and $T^{\prime}$ be defined as above. If there exists an optimal tour that contains $P$, then

$$
\begin{equation*}
2 \ell(S)+\ell(T)+\ell\left(T^{\prime}\right) \leq 3 \operatorname{opt}(G, \ell)+\ell\left(v_{2}, v_{3}\right) . \tag{32}
\end{equation*}
$$

Theorem 12. For a complete graph $G=(V, E)$ with an odd number of vertices and an edge length function $\ell: E \rightarrow$ $\mathbb{R}_{+}$, Algorithm TourOdd computes a 3/4-differential approximate tour of $(G, \ell)$ in polynomial time.

Acknowledgments This work was partially supported by the joint project of Kyoto University and Toyota Motor Corporation, titled "Advanced Mathematical Science for Mobility Society" and by KAKENHI.

## References

[1] Arora, Sanjeev. Polynomial time approximation schemes for Euclidean traveling salesman and other geometric problems.

```
Algorithm TourOdd
Input: A complete graph \(G=(V, E)\) with odd \(|V|\), and an edge length function \(\ell: E \rightarrow \mathbb{R}_{+}\).
Output: A tour \(T_{\text {apx }}\) in \(G\).
if \(n<17\) then
    Compute an optimal tour \(T_{\mathrm{opt}}\) of \((G, \ell)\) by exhaustive search.
    Output \(T_{\text {opt }}\) and halt.
else
    \(\mathcal{T}:=\emptyset\).
    for \(v_{1}, v_{2}, v_{3}\) and \(v_{4}\) in the 4-permutations of \(V\) do
        Compute a minimum weighted 2 -factor \(S\) among those containing \(\left\{\left(v_{1}, v_{2}\right),\left(v_{2}, v_{3}\right),\left(v_{3}, v_{4}\right)\right\}\).
        Compute a minimum weighted path cover \(T\) among those satisfying \(\left(v_{1}, v_{2}\right),\left(v_{2}, v_{3}\right) \in T\) and \(V_{1}(T)=V \backslash\left\{v_{2}\right\}\).
        Compute a minimum weighted path cover \(T^{\prime}\) among those satisfying \(\left(v_{2}, v_{3}\right),\left(v_{3}, v_{4}\right) \in T^{\prime}\) and \(V_{1}\left(T^{\prime}\right)=V \backslash\left\{v_{3}\right\}\).
        if \(S\) is a tour then
                \(\mathcal{T}:=\mathcal{T} \cup\{S\}\).
        else
            \(S_{1}, T_{1}, S_{2}, T_{2}:=\) FourPathCovers \((S, T)\).
                \(S_{1}^{\prime}, T_{1}^{\prime}, S_{2}^{\prime}, T_{2}^{\prime}:=\) FourPathCovers \(\left(S, T^{\prime}\right)\).
                Compute edge sets \(A_{1}, A_{2}, B_{1}, B_{2}, A_{1}^{\prime}, A_{2}^{\prime}, B_{1}^{\prime}\), and \(B_{2}^{\prime}\), which satisfy (27), (28), (29), (30), and (31).
                \(\mathcal{T}:=\mathcal{T} \cup\left\{S_{1} \cup A_{1}, S_{2} \cup A_{2}, T_{1} \cup B_{1}, T_{2} \cup B_{2}, S_{1}^{\prime} \cup A_{1}^{\prime}, S_{2}^{\prime} \cup A_{2}^{\prime}, T_{1}^{\prime} \cup B_{1}^{\prime}, T_{2}^{\prime} \cup B_{2}^{\prime}\right\}\).
        end if
    end for
    \(T_{\mathrm{apx}}:=\underset{T \in \mathcal{T}}{\operatorname{argmin}} \ell(T)\).
    Output \(T_{\mathrm{apx}}\) and halt.
    end if
```

Journal of the ACM, 45(5):753-782, 1998.
[2] Ausiello, Giorgio and Bazgan, Cristina and Demange, Marc and Paschos, Vangelis Th. Completeness in differential approximation classes. International Journal of Foundations of Computer Science, 16(06):1267-1295, 2005.
[3] Bellman, Richard. Dynamic programming treatment of the travelling salesman problem. Journal of the ACM (JACM), 9(1):61-63, 1962.
[4] Bland, Robert G and Shallcross, David F. Large travelling salesman problems arising from experiments in X-ray crystallography: a preliminary report on computation. Operations Research Letters, 8(3):125-128, 1989.
[5] Chlebík, Miroslav and Chlebíková", Janka. Approximation hardness of Travelling Salesman via weighted amplifiers. In International Computing and Combinatorics Conference, pages 115-127. Springer, 2019.
[6] Christofides, Nicos. Worst-case analysis of a new heuristic for the travelling salesman problem. Technical report, CarnegieMellon Univ Pittsburgh Pa Management Sciences Research Group, 1976.
[7] Cook, William J. In pursuit of the traveling salesman: mathematics at the limits of computation. Princeton University Press, 2011.
[8] Demange, Marc and Paschos, Vangelis Th. On an approximation measure founded on the links between optimization and polynomial approximation theory. Theoretical Computer Science, 158(1-2):117-141, 1996.
[9] Engebretsen, Lars and Holmerin, Jonas. Clique is hard to approximate within $n^{1-O(1)}$. In International Colloquium on Automata, Languages, and Programming, pages 2-12. Springer, 2000.
[10] Escoffier, Bruno and Monnot, Jérôme. A better differential approximation ratio for symmetric TSP. Theoretical Computer Science, 396(1-3):63-70, 2008.
[11] Grötschel, Martin and Jünger, Michael and Reinelt, Gerhard. Optimal control of plotting and drilling machines: a case study. Zeitschrift für Operations Research, 35(1):61-84, 1991.
[12] Hassin, Refael and Khuller, Samir. $z$-Approximations. Journal of Algorithms, 41(2):429-442, 2001.
[13] Held, Michael and Karp, Richard M. A dynamic program-
ming approach to sequencing problems. Journal of the Society for Industrial and Applied mathematics, 10(1):196-210, 1962.
[14] Lin, Shen and Kernighan, Brian W. An effective heuristic algorithm for the traveling-salesman problem. Operations research, 21(2):498-516, 1973.
[15] Little, John DC and Murty, Katta G and Sweeney, Dura W and Karel, Caroline. An algorithm for the traveling salesman problem. Operations research, 11(6):972-989, 1963.
[16] Monnot, Jérôme. Differential approximation results for the traveling salesman and related problems. Information Processing Letters, 82(5):229-235, 2002.
[17] Monnot, Jérôme and Paschos, Vangelis Th and Toulouse, Sophie. Approximation algorithms for the traveling salesman problem. Mathematical methods of operations research, 56(3):387-405, 2003.
[18] Monnot, Jérôme and Paschos, Vangelis Th and Toulouse, Sophie. Differential approximation results for the traveling salesman problem with distances 1 and 2. European Journal of Operational Research, 145(3):557-568, 2003.
[19] Monnot, Jérôme and Toulouse, Sophie. The traveling salesman problem and its variations. Paradigms of Combinatorial Optimization: Problems and New Approaches, pages 173-214, 2014.
[20] Papadimitriou, Christos H and Steiglitz, Kenneth. Combinatorial optimization: algorithms and complexity. Courier Corporation, 1998.
[21] Punnen, Abraham P. The traveling salesman problem: Applications, formulations and variations. In The traveling salesman problem and its variations, pages 1-28. Springer, 2007.
[22] Shmoys, DB and Lenstra, JK and Kan, AHG Rinnooy and Lawler, EL. The traveling salesman problem, volume 12. Wiley, 1985.


[^0]:    1 Research Institute for Mathematical Sciences, Kyoto University, Kyoto, Japan. \{ukiamano, makino\}@kurims.kyoto-u.ac.jp

