

Design of QoS-based Checkpoint Protocol for Multimedia Network Systems and Implementation on Java VM *

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1 Introduction

The advanced computer and network technologies have lead to the development of distributed systems. Here, an application is realized by multiple processes computing and communicating by exchanging messages through communication channels. Some mission-critical applications are required to be executed fault-tolerantly. One important method for fault-tolerance is checkpoint-recovery. For restarting execution correctly after recovery, a set of checkpoints taken by all the processes should form a *consistent global checkpoint* [1]. Distributed multimedia applications such as distance learning, tele-conference, tele-medicine and video on demand have recently been developed on communication networks. A multimedia message is so large that it is required to take checkpoints even during transmission and reception of the message. In addition, an application can accept a message even if a part of the message is lost. Based on the properties, the authors have proposed a measurement for consistency of a global checkpoint [2]. According to it, this paper discusses checkpoint protocols for multimedia network systems. These protocols are non-blocking for supporting realtime applications. Here, consistency and timeliness are QoS parameters.

2 Global Consistency

Let $\mathcal{S} = \langle \mathcal{V}, \mathcal{L} \rangle$ be a distributed system where $\mathcal{V} = \{p_1, \dots, p_n\}$ is a set of processes p_i and $\mathcal{L} \subseteq \mathcal{V}^2$ is a set of communication channels $\langle p_i, p_j \rangle$ from p_i to p_j . During failure-free execution, p_i takes a *checkpoint* c_i . A set $\{c_1, \dots, c_n\}$ is a *global checkpoint* C_V . Global consistency GC is determined by channel consistency CC for all the channels in \mathcal{L} . CC for $\langle p_i, p_j \rangle$ is determined by message consistency MC for all the messages transmitted through $\langle p_i, p_j \rangle$. Finally, MC for a message m is determined by timing relation between m and $C_{\langle p_i, p_j \rangle} = \{c_i, c_j\}$. The measurement of consistency in [2] is upper compatible with the conventional one in [1].

[Message consistency] A multimedia message m is decomposed into a sequence $\langle pa_1, \dots, pa_l \rangle$ of packets for transmission. Suppose p_i takes c_i between transmissions of pk_s and pk_{s+1} and p_j takes c_j between receptions of pk_t and pk_{t+1} . If $s > t$, $\{pk_{t+1}, \dots, pk_s\}$ is a set of lost packets which are not retransmitted after recovery. Thus, lost packets decrease MC . On the other hand, if $s < t$, $\{pk_{s+1}, \dots, pk_t\}$ is a set of orphan packets. These packets are surely retransmitted after recovery. Thus, orphan packets do not affect MC . Therefore, lost consistency is induced as a ra-

tio of value of lost packets to value of m . Since m is transmitted after compression, value of packets is not unique as in MPEG.

$$MC(m, s, t) = 1 - \frac{\sum_{k=t+1}^s \text{value}(pa_k)}{\text{value}(m)} \quad (1)$$

[Channel consistency] Here, \mathcal{M}_{ij} is a set of messages transmitted through $\langle p_i, p_j \rangle$.

$$CC(\langle p_i, p_j \rangle) = \prod_{m \in \mathcal{M}_{ij}} MC(m) \quad (2)$$

[Global consistency]

$$GC(C_V) = \left(\prod_{\langle p_i, p_j \rangle \in \mathcal{L}} CC(\langle p_i, p_j \rangle) \right)^{1/|\mathcal{L}|} \quad (3)$$

3 Basic Checkpoint Protocol

A basic checkpoint protocol \mathcal{P}_B is designed where GC is adapted as a QoS parameter. Though \mathcal{P}_B is based on a 3-phase coordinated checkpoint protocol, it is non-blocking. Each process is not required to suspend execution as in a conventional protocols for data communication systems. Here, a sequence number $seq(m)$ of m and $rvalue(pa_k, m) = \text{value}(pa_k) / \text{value}(m)$ are piggybacked to pa_k .

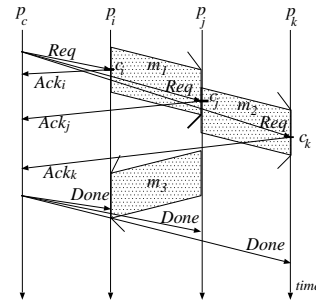


Figure 1: Basic protocol \mathcal{P}_B .

[Basic protocol \mathcal{P}_B (Figure 1)]

- 1) Let RC be required consistency. A coordinator p_c sends a request message Req to every $p_i \in \mathcal{V}$.
- 2) On receiving Req , p_i takes a tentative checkpoint tc_i and sends back an acknowledgement message Ack_i to p_c . For every $\langle p_i, p_j \rangle$ ($\langle p_j, p_i \rangle$), $seq(m_{ij})$ ($seq(m_{ji})$) and $tvalue(m_{ij}) = \sum \text{rvalue}(pa_k, m_{ij})$ ($tvalue(m_{ji}) = \sum \text{rvalue}(pa_k, m_{ji})$) for pa_k of the last message m_{ij} (m_{ji}) sent (received) before tc_i are piggybacked to Ack_i .
- 3) On receiving all Ack_i , p_c calculates GC . If $GC > RC$, p_c sends $Done$ to p_i . Otherwise, p_c sends $Cancel$ to p_i .
- 4) On receipt of $Done$, p_i changes tc_i to c_i . On receipt of $Cancel$, p_i discards tc_i . \square

*マルチメディアネットワークのための QoS に基づいたチェックポイントプロトコルの設計とその JavaVM への実装

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4 Extended Protocol

Though \mathcal{P}_B is non-blocking for supporting realtime multimedia applications, it is not certain to take C_V with required global consistency. According to the definition of GC , the less lost packets are, the higher global consistency we archive. Thus, the following modification in step 2) of \mathcal{P}_B for higher probability to take C_V and higher $GC(C_V)$ is introduced.

- If p_i is sending a message, p_i takes tc_i soon.
- Otherwise, p_i postpones taking tc_i for ΔT_i . If p_i starts sending another message or p_i starts receiving additional message while receiving a message, p_i takes tc_i .

Here, we introduce an additional QoS parameter τ for timeliness. p_c is required to receive Ack_i within τ since the transmission of Req . Thus, $\Delta T_i = \tau - 2\delta_i$ where δ_i is transmission delay between p_c and p_i .

[Extended protocol \mathcal{P}_E]

- 1) Let RC and τ are required consistency and timeliness. p_c sends Req to every $p_i \in \mathcal{V}$. τ is piggybacked back to Req .
- 2) On receiving Req , p_i takes tc_i as follows:
 - 2-1) If p_i is sending a message, p_i takes tc_i .
 - 2-2) Otherwise, p_i postpones taking tc_i for ΔT_i . During this period,
 - if p_i is receiving a message and starts sending another message, p_i takes tc_i immediately.
 - if p_i is not communicating and starts sending or receiving a message, p_i takes tc_i immediately.

On taking tc_i , p_i sends Ack_i as in step 2) of \mathcal{P}_B .

- 3) and 4) are same as in \mathcal{P}_B . \square

5 Implementation and Evaluation

The proposed protocol for taking checkpoints in a multimedia network system is implemented on JavaVM. JavaVM is an interpreter for programs written in Java language and the execution environment is independent of the architecture, i.e. hardware architecture and software one including an operating system. Hence, it is possible to achieve wide interoperability if the proposed protocol is implemented in JavaVM.

For taking a checkpoint c_i of a process p_i , i.e. storing state information of p_i at c_i for recovery from a certain failure in a system, serialization which is a function provided by Java environment is adopted. Here, each object for an application implements a Serializable class. By invoking a method `WriteObject` which is a method in `ObjectOutputStream` class, an object is transformed to a byte sequence from which an original object is achieved when a recovery procedure, `ObjectOutputStream` is invoked later. A serialized object, i.e. a byte sequence, is stored into a stable storage.

In this section, we evaluate an overhead for taking a checkpoint implemented by the above method to determine whether it is reasonable for a multimedia network system to take a checkpoint while an object is transmitting and/or receiving a multimedia message.

Here, it is assumed that a multimedia message m is transmitted from a computer M_i to another one M_j both of which are connected to a Ethernet LAN.

Hence, m is decomposed into fully filled Ethernet frames, i.e. each of them is a 1500 byte packet. While transmitting m , M_j takes a local checkpoint by using a serialization mechanism. If the size of a communication buffer is not sufficient, some packets are lost and taking a checkpoint during a communication event is not reasonable. Otherwise, our proposed method is acceptable.

The specification of two computers and NICs attached to the computers is as follows:

M_i : Celeron 1.2GHz CPU, 512MByte Memory, Windows2000 SP3 and Planex FNW-9800T 100Base-TX Ethernet NIC.

M_j : Crusoe 800MHz CPU, 256MB Memory, WindowsXP Home Edition and Realtek RTL8139/810 Family PCI 100Base-TX Ethernet NIC.

Figure 2 shows the relation between size of an object and required time duration to store the serialized object into a storage. The time duration T is almost proportional to the size S of an object: $T = 92.5[msec/Mbyte]S$. The maximum size of an object supported by JavaVM is 60MByte. Even though the object size is 60MByte and packet transmission interval in M_j is set as minimum value, i.e. setting a parameter as `NoWait` and the achieved interval is about 30.0msec, no packets are lost while taking a checkpoint. Therefore, it is reasonable to introduce our method to a multimedia network system.

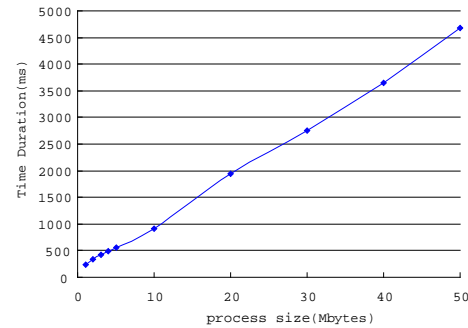


Figure 2: Time Duration for Taking Checkpoint.

6 Concluding Remarks

This paper proposed two checkpoint protocols for multimedia network systems. These protocols are based on a novel global consistency as a QoS parameter. For higher consistency, delayed checkpointing is introduced with another QoS parameter, timeliness. Finally, we evaluate the processing overhead to take a checkpoint and find that the proposed method is acceptable for multimedia network systems.

References

- [1] Chandy, K.M. and Lamport, L., "Distributed Snapshot: Determining Global States of Distributed Systems," ACM Trans. on Computer Systems, Vol. 3, No. 1, pp. 63-75 (1985).
- [2] Hiraga, K. and Higaki, H., "Consistent Global Checkpoint in Multimedia Network Systems," Proc. of the 8th Workshop on Multimedia Communication and Distributed Processing Systems, pp. 253-258 (2000).