# **QoS Based Group Communication**

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#### Abstract

In distributed applications, a group of multiple processes are cooperating by exchanging multimedia messages. The multimedia objects are longer than traditional messages. If messages transmitted in a network are causally delivered by using traditional group protocols, computation and communication overheads are increased due to large size of multimedia data. In this paper, we discuss a protocol to causally deliver multimedia objects.

### 1 Introduction

In distributed applications, a group of multiple processes are cooperating. In the group communication, a group is first established among multiple processes and then messages sent by processes are causally delivered to destination processes in the group. A message  $m_1$  causally precedes another message  $m_2$  if and only if (iff) a sending event of  $m_1$  happens before a sending event of  $m_2$ .

In distributed applications, various kinds of multimedia objects like image and video are exchanged among multiple processes in the group. Multimedia objects are structured and are larger than traditional data messages.

An object is decomposed into a sequence of messages in order to transmit the object in a network. A message is a unit of data transmission. If a pair of objects  $o_1$  and  $o_2$  are transmitted by processes  $p_1$  and  $p_2$ . The messages decomposed from  $o_1$  and  $o_2$  are causally delivered to every common destination process  $p_3$  of  $o_1$  and  $o_2$ according to the traditional group protocols. The messages of the object  $o_1$  can be delivered independently of the object  $o_2$  if  $o_1$  is manipulated independently of  $o_2$ in an application. In another application, the top message in a message sequence decomposed from an object o<sub>1</sub> is required to be delivered before the top message of another object  $o_2$  while the other messages can be delivered in any order. Thus, we define new types of precedent relations named Object-(O-)precedent relation of messages based on the object concept. According to the O-precedent relations, the destination processes deliver messages of objects. A pair of messages not to be ordered in the O-precedent relations can be delivered in any order even if one of the messages causally precedes the other message according to the traditional network-level destination. Only precedent relations among top messages of objects are discussed in the paper. In order to support QoS required by applications, message sequence of objects should be related at a smaller granularity. In the paper, we discuss how related granules of objects are in the networks.

### 2 System Model

Distributed applications are realized by cooperation of a group of multiple application processes. Application processes exchange objects including multimedia data with the other processes in the group by using the network. An application process is supported by a system process. The process  $p_t$  takes an object from the application process and then delivers the object to the

system processes supporting the destination application processes by using the basic communication service supported by the network. From here, let a term *process* mean a system process.

A data unit exchanged among processes is a *message*. Messages are not lost and maximum delay time between every pair of processes is bounded in the network.

An object o is decomposed into a sequence of messages by a source process and the messages are delivered to the destination processes. Here,  $m_1$  and  $m_k$  are the top and last messages of the object o. A destination process assembles received messages into an object and then delivers the object to the application process. The cooperation of the processes is coordinated by a group protocol which supports the reliable, efficient communication service by taking usage of the network service.

### 3 Object-Precedency

We discuss how a process sends and receives multimedia objects in a group G of multiple processes  $p_1, ..., p_n$  (n > 1). In order to increase the throughput and reduce the response time, sending and receiving events of objects are interleaved if there is no precedent relation among objects.

As presented here, a way on how a pair of objects  $o_1$  and  $o_2$  are interrelated depends on when processes  $p_s$  and  $p_t$  start and finish sending and receiving the objects. We discuss how a pair of objects  $o_1$  and  $o_2$  can be causally ordered. Let  $ss_t(o)$  and  $es_t(o)$  denote events that a process  $p_t$  starts and finishes sending an object o, respectively. In fact,  $ss_t(o)$  and  $es_t(o)$  show events that the top and last messages of the object o are sent by  $p_t$ , respectively.  $sr_t(o)$  and  $er_t(o)$  also mean the receipt events of the top and last messages of the object o, respectively. Let  $sr_t(o)$  and  $er_t(o)$  denote events that  $p_t$  starts and finishes receiving the object o.

[**Definition**] Let  $o_1$  and  $o_2$  be a pair of objects  $o_1$  and  $o_2$  sent by processes  $p_s$  and  $p_t$ , respectively:

- 1  $o_1$  top-precedes  $o_2$   $(o_1 \rightharpoonup o_2)$  iff
  - $\diamond sr_t(o_1)$  happens before  $(\prec) ss_t(o_2)$  if  $p_s \neq p_t$ .
  - $\diamond ss_s(o_1) \prec ss_t(o_2) \text{ if } p_s = p_t.$
- 2  $o_1$  tail-precedes  $o_2$   $(o_1 \rightarrow o_2)$  iff
  - $\diamond er_t(o_1) \prec es_t(o_2) \text{ if } p_s \neq p_t.$
  - $\diamond \ es_s(o_1) \prec es_t(o_2) \ \text{if} \ p_s = p_t.$
- 3  $o_1$  partially precedes  $o_2$   $(o_1 \rightarrow o_2)$  iff  $o_1 \rightarrow o_2$ ,  $o_1 \rightarrow o_2$ , and  $o_1$  is interleaved with  $o_2$   $(o_1 || o_2)$ .
- 4  $o_1$  fully precedes  $o_2$   $(o_1 \Rightarrow o_2)$  iff
  - $\diamond er_s(o_1) \prec ss_t(o_2) \text{ if } p_s \neq p_t.$
  - $\diamond \ es_s(o_1) \prec ss_t(o_2) \ \text{if} \ p_s = p_t.$
- 5  $o_1$  inclusively precedes  $o_2$   $(o_1 \supset o_2)$  iff  $o_1 \rightharpoonup o_2$  and  $o_1 \multimap o_2$ .
- 6  $o_1$  exclusively precedes  $o_2$   $(o_1 \square o_2)$  iff  $o_1 \neg o_2$  and  $o_2 \rightharpoonup o_1.\square$

The top, tail, fully, partially, inclusively, and exclu-

sively precedent relations defined here are referred to as object-causally precedent (O-precedent) relation. Here,  $o_1 \leadsto o_2$  shows that  $o_1$  O-precedes  $o_2$ , i.e.  $\leadsto \in \{ \rightharpoonup, \neg, \Rightarrow, \rightarrow, \supset, \sqsupset \}$ . The process  $p_u$  is required to deliver messages of objects  $o_1$  and  $o_2$  so as to satisfy the O-precedent relation  $\leadsto$  between  $o_1$  and  $o_2$ .

# 4 Granularity of Synchronization

## 4.1 Segments

A synchronization (syn) message is transmitted to synchronize communication of  $o_1$  and  $o_2$  at a smaller granularity level. A process sends a syn message each time the process sends some number of messages for each object. Non-synchronization messages are referred to as normal ones. A sequence of messages of the object is decomposed into subsequences which are named segments. Each segment of messages starts at a syn message and ends at a next synchronization one. Suppose an object o is a sequence of messages  $\langle ..., m_i, m_{i+1}, ..., m_j, ... \rangle$ where  $m_i$  and  $m_j$  are syn messages and  $m_{i+1}, ..., m_{j+1}$ are normal messages. Here, a subsequence  $\langle m_{i+1}, ...,$  $m_i$  is a segment. If  $m_i$  is the top message of  $o_1$ ,  $\langle m_i, m_i \rangle$  $m_{i+1}, ..., m_i$  is a segment. Thus, the object o can be considered to be a sequence of segments. A process  $p_s$  sends an object  $o_s$  to another process  $p_t$ . The object  $o_s$ is decomposed into a sequence of seven messages  $m_1, ...,$  $m_7$ . Here,  $m_1$ ,  $m_4$ , and  $m_7$  are syn messages. In fact,  $m_1$  and  $m_7$  are the top and last messages of the object  $o_s$ , respectively. Thus, the object  $o_s$  is decomposed into a sequence of two segments  $s_1$  and  $s_2$  where  $s_1 = \langle m_1, m_2 \rangle$  $m_2, m_3, m_4$  and  $s_2 = \langle m_5, m_6, m_7 \rangle$ .

[Definition] Let  $\langle s_1, \dots \rangle$  and  $\langle t_1, \dots \rangle$  be a pair of sequences of segments of objects  $o_s$  and  $o_t$ , respectively. Suppose  $o_s$  O-precedes  $o_t$  ( $o_s \leadsto o_t$ ).

- A subsequence ⟨s<sub>i</sub>, s<sub>i+1</sub>, ..., s<sub>l</sub>⟩ of segments of o<sub>s</sub> and a segment t<sub>k</sub> of o<sub>t</sub> are synchronization blocks iff s<sub>i-1</sub> fully precedes t<sub>k</sub> (s<sub>i-1</sub>⇒t<sub>k</sub>), s<sub>i</sub> partially precedes t<sub>k</sub> (s<sub>i</sub>→t<sub>k</sub>), every s<sub>h</sub> inclusively precedes t<sub>k</sub> (s<sub>h</sub>⊃t<sub>k</sub>) (h=i+1, ..., l), and s<sub>l+1</sub> ⊅ t<sub>k</sub>.
- 2. A segment  $s_k$  of  $o_s$  and a subsequence  $\langle t_i, ..., t_l \rangle$  of segments of  $o_t$  are synchronization blocks iff  $s_k$  exclusively precedes  $t_h$   $(s_k \Box t_h)$   $(h = i, ..., l-1), s_k$   $\not \supseteq t_{i-1}$ , and  $s_k \to t_l . \square$

Let  $o_s$  and  $o_t$  be objects where  $o_s$  O-precedes  $o_t$   $(o_s \leadsto o_t)$ . Let  $\langle S_1, \, ..., \, S_n \rangle$  and  $\langle T_1, \, ..., \, T_n \rangle$  be sequences of synchronization blocks of objects  $o_s$  and  $o_t$ , respectively. Here, each pair of blocks  $s_i$  and  $T_i$  are synchronization blocks. If each of synchronization blocks  $S_i$  and  $T_i$  includes one segment, a pair of objects  $o_s$  and  $o_t$  are referred to as  $fully \, synchronized$ .

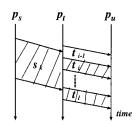


Figure 1: Synchronization blocks

#### 4.2 Synchronization of blocks

A process  $p_t$  sends a syn message if some condition on messages which  $p_t$  is receiving is satisfied. For example, suppose a process  $p_s$  is receiving messages of an object  $o_s$ ,  $p_t$  is sending messages of an object  $o_t$ , and  $o_s$  O-precedes  $o_t (o_s \leadsto o_t)$ . The process  $p_t$  sends a syn message each time  $p_t$  receives a syn message from  $p_s$ . Here,  $o_s$  and  $o_t$  are fully synchronized. The process  $p_t$  can send one syn message of  $o_t$  every two segments  $p_t$  receives from  $p_s$ . The process  $p_t$  can also send a pair of syn messages of  $o_t$  while  $p_t$  receives one segment. Here, we introduce a blocking factor  $b_i$  for each pair of synchronization blocks  $S_i$  and  $T_i$  of objects  $o_s$  and  $o_t$ , respectively, where  $o_s \leadsto o_t$ . The blocking factor  $b_i$  is defined to be  $||T_i||/||S_i||$ . Here, a notation ||B|| shows number of segments in a block B. If  $b_i=1$ ,  $o_s$  and  $o_t$  are fully synchronized. If  $b_i>1$ ,  $p_t$ sends more number of syn messages than  $p_s$ . Otherwise,  $p_t$  sends less number of syn messages than  $p_t$ .

#### 4.3 QoS precedence

We assume each message has the same size. Here, let g(s) show the number of messages included in the segment s. Suppose the objects  $o_1$  and  $o_2$  are fully synchronized and a pair of segments  $s_{1i}$  and  $s_{2i}$  are synchronization blocks. Suppose a process  $p_s$  sends a video object  $o_1$  to a pair of processes  $p_t$  and  $p_u$  and the process  $p_t$  sends a video object  $o_2$  to  $p_u$ . The objects  $o_1$  and  $o_2$  are simultaneously displayed in  $p_u$ . Suppose that  $o_1$  and  $o_2$  have different frame rates  $f_1$  and  $f_2$ , respectively. The blocking factor  $b_{12} = g(s_{2i})/g(s_{1i})$  is required to be  $f_2/f_1$ . Here, let  $b_{12}$  be a blocking function of  $o_2$  to  $o_2$ .

[**Definition**] An object  $o_1$  Q-precedes another object  $o_2$   $(o_1 \stackrel{Q}{\leadsto} o_2)$  iff  $o_1 \leadsto o_2$  and Q shows a blocking factor.  $\Box$ 

Suppose an object  $o_1$  Q-precedes another object  $o_2$  ( $o_1$  Q- $o_2$ ) where a process  $p_t$  sends  $o_2$  while receiving  $o_1$  from a process  $p_s$ . Suppose  $p_t$  receives a synchronization(syn) messages  $m_1$  from  $p_s$  and then receives messages in a segment  $s_1$ . The process  $p_t$  starts sending a new segment  $s_2$  of  $o_2$ , i.e.  $p_t$  sends a syn message  $m_2$ . Then,  $p_t$  receives a syn message  $m_1$  from  $p_s$ . Here, let  $h(s_2)$  show the number of messages which  $p_t$  has sent so far. If  $h(s_1)/g(s_2) \geq Q$ ,  $p_t$  finishes sending  $s_2$  by sending a syn message  $m_4$ . Suppose a process  $p_s$  sends  $o_1$  to a pair of precesses  $p_t$  and  $p_u$  and the process  $p_t$  sends an object  $o_2$  to  $p_u$ . Here,  $p_u$  receives  $o_1$  and  $o_2$ . Suppose  $o_1 \leadsto o_2$ . If  $p_u$  delivers segments of  $o_1$  and  $o_2$  according to the causality of segments,  $o_1$  and  $o_2$  are delivered in  $p_u$  so as to satisfy  $o_1 \stackrel{Q}{\leadsto} o_2$ .

[**Definition**] If  $o_1 \stackrel{Q_1}{\leadsto} o_2$  and  $o_2 \stackrel{Q_2}{\leadsto} o_3$ ,  $o_1 \stackrel{Q}{\leadsto} o_3$  where  $Q = Q_1 * Q_2$ .  $\square$ 

#### 5 Concluding Remarks

We defined the O-precedent relations among multimedia objects. In addition, we discussed synchronization (syn) messages in order to synchronize multiple objects which are O-preceded at a smaller granularity level.

#### References

[1] Shimamura, K., Tanaka, K., and Takizawa, M., "Group Protocol for Exchanging Multimedia Objects in a Group," Proc. of ICDCS Int'l Workshop on Group Communications and Computations (IWGCC), 2000, C33–C40.